

```

> restart :
> H(s) := 
$$\frac{40 e^{-2s}}{(s-3)(s-2)^3}$$


$$H(s) := \frac{40 e^{-2s}}{(s-3)(s-2)^3}$$
 (1)
> F(s) :=  $\frac{40}{(s-3)}$ ; G(s) :=  $\frac{\exp(-2s)}{(s-2) \cdot 3}$ ;

$$F(s) := \frac{40}{s-3}$$


$$G(s) := \frac{e^{-2s}}{(s-2)^3}$$
 (2)
> with(inttrans) :
> f(t) := invlaplace(F(s), s, t);

$$f(t) := 40 e^{3t}$$
 (3)
> g(t) := invlaplace(G(s), s, t);

$$g(t) := \frac{1}{2} \text{Heaviside}(t-2) (t-2)^2 e^{2t-4}$$
 (4)
> h(t) := simplify(int(40·exp(3·(t-tau))·( $\frac{1}{2}$ )·Heaviside(tau-2)·(tau-2)·2·exp(2·tau-4), tau=0..t));

$$h(t) := -20 \text{Heaviside}(t-2) (2 e^{2t-4} - 2 e^{2t-4} t + e^{2t-4} t^2 - 2 e^{3t-6})$$
 (5)
> comprobacion := invlaplace(H(s), s, t);

$$\text{comprobacion} := 20 \text{Heaviside}(t-2) (2 e^{3t-6} - e^{2t-4} (t^2 - 2t + 2))$$
 (6)
> invlaplace( $\frac{\exp(-s)}{s}$ , s, t);

$$\text{Heaviside}(t-1)$$
 (7)
> restart :
> sistema :=  $\frac{d}{dt} y_1(t) = 2 y_1(t) + 2 y_2(t)$ ,  $\frac{d}{dt} y_2(t) = 4 y_1(t) + 4 y_2(t)$  : sistema1; sistema2;

$$\frac{d}{dt} y_1(t) = 2 y_1(t) + 2 y_2(t)$$


$$\frac{d}{dt} y_2(t) = 4 y_1(t) + 4 y_2(t)$$
 (8)
> AA := array([ [2, 2], [4, 4] ]);

$$AA := \begin{bmatrix} 2 & 2 \\ 4 & 4 \end{bmatrix}$$
 (9)
> II := array([ [1, 0], [0, 1] ]);

$$II := \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$
 (10)
> sImenosAA := evalm(s·II - AA);

```

$$sImenosAA := \begin{bmatrix} s-2 & -2 \\ -4 & s-4 \end{bmatrix} \quad (11)$$

> with(linalg) :

> INVsiImenosAA := inverse(sImenosAA);

$$INVsiImenosAA := \begin{bmatrix} \frac{s-4}{s(s-6)} & \frac{2}{s(s-6)} \\ \frac{4}{s(s-6)} & \frac{s-2}{s(s-6)} \end{bmatrix} \quad (12)$$

> with(inttrans) :

> MatExp := map(invlaplace, INVsiImenosAA, s, t);

$$MatExp := \begin{bmatrix} \frac{2}{3} + \frac{1}{3} e^{6t} & \frac{1}{3} e^{6t} - \frac{1}{3} \\ \frac{2}{3} e^{6t} - \frac{2}{3} & \frac{1}{3} + \frac{2}{3} e^{6t} \end{bmatrix} \quad (13)$$

> ExpMat := exponential(AA, t);

$$ExpMat := \begin{bmatrix} \frac{2}{3} + \frac{1}{3} e^{6t} & \frac{1}{3} e^{6t} - \frac{1}{3} \\ \frac{2}{3} e^{6t} - \frac{2}{3} & \frac{1}{3} + \frac{2}{3} e^{6t} \end{bmatrix} \quad (14)$$

> restart :

> with(PDEtools);

[CanonicalCoordinates, ChangeSymmetry, CharacteristicQ, CharacteristicQInvariants, ConservedCurrentTest, ConservedCurrents, ConsistencyTest, D_Dx, DeterminingPDE, Eta_k, Euler, FromJet, InfinitesimalGenerator, Infinitesimals, IntegratingFactorTest, IntegratingFactors, InvariantSolutions, InvariantTransformation, Invariants, Laplace, Library, PDEplot, PolynomialSolutions, ReducedForm, SimilaritySolutions, SimilarityTransformation, SymmetrySolutions, SymmetryTest, SymmetryTransformation, TWSolutions, ToJet, build, casesplit, charstrip, dchange, dcoeffs, declare, diff_table, difforder, dpolyform, dsubs, mapde, separability, splitstrip, splitsys, undeclare] (15)

> EcuacionDerivadasParciales := diff(F(x, y), x\$2) - 6·diff(F(x, y), x, y) + 8·diff(F(x, y), y\$2) = 0;

$$EcuacionDerivadasParciales := \frac{\partial^2}{\partial x^2} F(x, y) - 6 \left(\frac{\partial^2}{\partial y \partial x} F(x, y) \right) + 8 \left(\frac{\partial^2}{\partial y^2} F(x, y) \right) = 0 \quad (16)$$

> Solucion := pdsolve(EcuacionDerivadasParciales);

$$Solucion := F(x, y) = _F1(y + 2x) + _F2(y + 4x) \quad (17)$$

> EDenDP := diff(y(x, t), t\$2) + 4·diff(y(x, t), x, t) + 4·diff(y(x, t), x\$2) = 0;

$$EDenDP := \frac{\partial^2}{\partial t^2} y(x, t) + 4 \left(\frac{\partial^2}{\partial x \partial t} y(x, t) \right) + 4 \left(\frac{\partial^2}{\partial x^2} y(x, t) \right) = 0 \quad (18)$$

> SOL := pdsolve(EDenDP);

$$SOL := y(x, t) = _F1(2t - x) + _F2(2t - x)x \quad (19)$$

$$\frac{\partial^2 T(x, t)}{\partial x^2} + \frac{\partial T(x, t)}{\partial t} = T(x, t)$$

> ED := diff(T(x, t), x\$2) + diff(T(x, t), t) - T(x, t);

$$ED := \frac{\partial^2}{\partial x^2} T(x, t) + \frac{\partial}{\partial t} T(x, t) - T(x, t) = 0 \quad (20)$$

> SolGral := build(pdsolve(ED));

$$SolGral := T(x, t) = \frac{e^{\sqrt{-c_1} x} C3 e^t C1}{e^{t-c_1}} + \frac{C3 e^t C2}{e^{\sqrt{-c_1} x} e^{t-c_1}} \quad (21)$$

>

>

>

>