

$$x_1(t) \quad \frac{dx_1}{dt} = 3x_1 + 4x_2 + e^{3t} + 4t^2 \quad x_1(0) = 5$$

$$x_2(t) \quad \frac{dx_2}{dt} = 2x_1 + 5x_2 + 6t + 8 \quad x_2(0) = -6$$

$\mathcal{S}(z) \in \mathcal{D}\mathcal{O}(1)$  & cc NH

$$\frac{d}{dt} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} = \begin{bmatrix} 3 & 4 \\ 2 & 5 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} + \begin{bmatrix} e^{3t} + 4t^2 \\ 6t + 8 \end{bmatrix} \quad \bar{x}(0) = \begin{bmatrix} 5 \\ -6 \end{bmatrix}$$

$$\frac{d}{dt} \bar{x}(t) = A \bar{x}(t) + b(t)$$

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$$\bar{x}(t) = [e^{At}] \bar{x}(0) + \int_0^t [e^{A(t-z)}] b(z) dz$$

$$\left[ \int_0^t [e^{A(t-z)}] b(z) dz \right]_{t=0} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

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$$x_2(t) \quad \frac{dx_2}{dt} = 2x_1 + 5x_2 + 6t + 8 \quad x_2(0) = -6$$

$$x_2 = \frac{1}{4} \left( \frac{dx_1}{dt} - 3x_1 - e^{3t} - 4t^2 \right)$$

$$x_2 = \frac{1}{4} \frac{dx_1}{dt} - \frac{3}{4}x_1 - \frac{1}{4}e^{3t} - t^2$$

→  $\frac{dx_2}{dt} = \frac{1}{4} \frac{d^2x_1}{dt^2} - \frac{3}{4} \frac{dx_1}{dt} - \frac{3}{4}e^{3t} - 2t$

$$\frac{1}{4} \frac{d^2x_1}{dt^2} - \frac{3}{4} \frac{dx_1}{dt} - \frac{3}{4} e^{3t} - 2t =$$

$$2x_1 + 5 \left( \frac{1}{4} \frac{dx_1}{dt} - \frac{3}{4} x_1 - \frac{1}{4} e^{3t} - t^2 \right) + 6t + 8$$

$$\frac{d^2x_1}{dt^2} - 3 \frac{dx_1}{dt} - 3e^{3t} - 8t = 8x_1 + 5 \frac{dx_1}{dt} - 15x_1 - 5e^{3t} - 20t^2 + 24t + 32$$

$$\frac{d^2x_1}{dt^2} - 8 \frac{dx_1}{dt} + 7x_1 = -2e^t + 32t - 20t^2 + 32$$

$$x_1 =$$

$$x_2 =$$