

```

> restart
> f(t) := 1
f(t) := 1
(1)

> with(inttrans);
[addtable, fourier, fouriercos, fouriersin, hankel, hilbert, invfourier, invhilbert, invlaplace,
invmellin, laplace, mellin, savetable]
(2)

> F(s) := laplace(f(t), t, s)
F(s) :=  $\frac{1}{s}$ 
(3)

> g(t) := t3;
g(t) :=  $t^3$ 
(4)

> G(s) := laplace(g(t), t, s)
G(s) :=  $\frac{6}{s^4}$ 
(5)

> h(t) := exp(4*t)
h(t) :=  $e^{4t}$ 
(6)

> H(s) := laplace(h(t), t, s)
H(s) :=  $\frac{1}{s-4}$ 
(7)

> j(t) := cos(5*t);
j(t) :=  $\cos(5t)$ 
(8)

> J(s) := laplace(j(t), t, s)
J(s) :=  $\frac{s}{s^2+25}$ 
(9)

> k(t) := sin(5*t);
k(t) :=  $\sin(5t)$ 
(10)

> K(s) := laplace(k(t), t, s)
K(s) :=  $\frac{5}{s^2+25}$ 
(11)

>

```