



$$x(t) + \int_0^t \tau e^{2\tau} x(t-\tau) d\tau = t e^{2t}$$

$$\mathcal{L}\left\{x(t) + \int_0^t \tau e^{2\tau} x(t-\tau) d\tau\right\} = \mathcal{L}\left\{t e^{2t}\right\}$$

$$X(s) + \mathcal{L}\left\{(t e^{2t}) * x(t)\right\} = \frac{1}{(s-2)^2}$$

$$X(s) + \mathcal{L}\{t e^{2t}\} \cdot X(s) = \frac{1}{(s-2)^2}$$

$$X(s) + \frac{1}{(s-2)^2} \cdot X(s) = \frac{1}{(s-2)^2}$$

$$X(s) \left(1 + \frac{1}{(s-2)^2}\right) = \frac{1}{(s-2)^2}$$

$$X(s) = \frac{\frac{1}{(s-2)^2}}{\left(1 + \frac{1}{(s-2)^2}\right)}$$

$$X(s) = \frac{\frac{1}{\cancel{(s-2)^2}}}{\frac{(s-2)^2 + 1}{\cancel{(s-2)^2}}} \Rightarrow \frac{1}{(s-2)^2 + 1}$$

$$\mathcal{L}^{-1}\{X(s)\} = \mathcal{L}^{-1}\left\{\frac{1}{(s-2)^2 + 1}\right\}$$

$$x(t) = e^{2t} \sin(t)$$

$$\mathcal{L}^{-1} \left\{ F(s) \cdot G(s) \right\} = \int_0^t f(z) \cdot g(t-z) dz$$

$f(t) * g(t)$

$$\mathcal{L}^{-1} \left\{ \frac{b}{s^2 + b^2} \right\} = \sin(bt)$$

$$\mathcal{L}^{-1} \left\{ \frac{b}{(s-a)^2 + b^2} \right\} = e^{at} \sin(bt)$$

$y(x, t)$ incógnita

$$\frac{\partial^2 y}{\partial x^2} - q \frac{\partial y}{\partial t} = 0$$

Método de Separación Variables para ED en \mathbb{D}^2

• prueba y error

• hipótesis inicial

$$y(x, t) = F(x) G(t) \quad \left\{ \begin{array}{l} \frac{F}{G} \quad F + G \\ F(x)^t \quad G(t)^* \\ L F - L G \end{array} \right.$$

• sustituimos la hipótesis y sus derivadas parciales en la ED en \mathbb{D}^2

• Separar miembro a miembro.

$$\frac{\partial^2 y}{\partial x^2} - q \frac{\partial y}{\partial t} = 0 \quad y(x, t) = F(x) G(t)$$

$$\frac{\partial y}{\partial x} = F'(x) G(t) \quad \frac{\partial y}{\partial t} = F(x) G'(t)$$

$$\frac{\partial^2 y}{\partial x^2} = F''(x) G(t)$$

$$F''(x) G(t) - q F(x) G'(t) = 0$$

$$F''(x) G(t) = q F(x) G'(t)$$

$$\boxed{\frac{F''(x)}{q F(x)} = \frac{G'(t)}{G(t)}} \quad \text{razón (\# abstracto)}$$

$$\frac{F''(x)}{q F(x)} = \alpha \quad \frac{G'(t)}{G(t)} = \alpha$$

$$\frac{d^2 F}{dx^2} = q \alpha F$$

$$\text{EDO}(2) \text{ LCC H.}$$

$$\frac{dG}{dt} = \alpha G$$

$$\text{EDO}(1) \text{ LCC H.}$$

$$y(x, t) = F(x) \cdot G(t)$$

$$\frac{d^2 F}{dx^2} - q \alpha F = 0$$

$$\frac{dG}{dt} - \alpha G = 0$$

$$\alpha = 0$$

$$\frac{d^2 F}{dx^2} = 0 \rightarrow \frac{dF}{dx} = k_1 \rightarrow F(x) = k_1 x + k_2$$

$$\frac{dG}{dt} = 0 \rightarrow G(t) = C_1 \quad y = \overset{\alpha=0}{(k_1 x + k_2)} C_1$$

$$\alpha > 0 \quad \alpha = \beta^2 \quad \forall \beta \neq 0 \in \mathbb{R}$$

$$\frac{d^2 F(x)}{dx^2} - q \beta^2 F(x) = 0$$

$$\frac{dG}{dt} - \beta^2 G = 0$$

$$m^2 - q \beta^2 = 0$$

$$G(t) = C_1 e^{\beta^2 t}$$

$$(m - 3\beta)(m + 3\beta) = 0$$

$$m_1 = 3\beta \quad m_2 = -3\beta$$

$$F(x) = \underset{\alpha > 0}{k_1} e^{3\beta x} + k_2 e^{-3\beta x}$$

$$\underset{\alpha > 0}{y}(x, t) = \left(k_1 e^{3\beta x} + k_2 e^{-3\beta x} \right) C_1 e^{\beta^2 t}$$

$$\alpha < 0 \quad \alpha = -\beta^2 \quad \forall \beta \neq 0 \in \mathbb{R}$$

$$\frac{d^2 F}{dx^2} + q\beta^2 F = 0 \quad \frac{dG}{dt} + \beta^2 G = 0$$

$$m^2 + q\beta^2 = 0$$

$$G(t) = C_1 e^{-\beta^2 t}$$

$$F(x) = k_1 \cos(\beta x) + k_2 \sin(\beta x)$$

$$y(x, t) = \left(k_1 \cos(\beta x) + k_2 \sin(\beta x) \right) C_1 e^{-\beta^2 t}$$

$$y = C_{10} e^{-\beta^2 t} \cos(\beta x) + C_{20} e^{-\beta^2 t} \sin(\beta x)$$

$$\frac{\partial^2 y}{\partial x^2} - q \frac{\partial y}{\partial t} = 0$$

$$\frac{\partial y}{\partial x} = \left(C_{10} e^{-\beta^2 t} \right) (-\beta \sin(\beta x)) + C_{20} e^{-\beta^2 t} (\beta \cos(\beta x))$$

$$\frac{\partial y}{\partial x} = -\beta C_{10} e^{-\beta^2 t} \sin(\beta x) + \beta C_{20} e^{-\beta^2 t} \cos(\beta x)$$

$$\frac{\partial^2 y}{\partial x^2} = -\beta^2 C_{10} e^{-\beta^2 t} \cos(\beta x) - \beta^2 C_{20} e^{-\beta^2 t} \sin(\beta x)$$

$$-q \frac{\partial y}{\partial t} = +C_{10} \cos(\beta x) (\beta^2 e^{-\beta^2 t}) + C_{20} \sin(\beta x) (\beta^2 e^{-\beta^2 t})$$

$$\frac{\partial^2 y}{\partial x^2} - q \frac{\partial y}{\partial t} = (0) e^{-\beta^2 t} \cos(\beta x) + (0) e^{-\beta^2 t} \sin(\beta x)$$

$$\frac{\partial^2 y}{\partial x^2} - q \frac{\partial y}{\partial t} = 0.$$