

$$\frac{dx_1(t)}{dt} = x_2(t) \quad x_1(0) = 5$$

$$\frac{dx_2(t)}{dt} = -x_1(t) \quad x_2(0) = -5$$

$$\frac{d^2 x_1(t)}{dt^2} = -x_1(t)$$

Exo 2) LCC4 $\frac{d^2 x_1(t)}{dt^2} + x_1(t) = 0$

$$M^2 + 1 = 0$$

$$M_1 = i \quad M_2 = -i$$

$$x_1(t) = C_1 \cos(t) + C_2 \sin(t)$$

$$x_2(t) = -C_1 \sin(t) + C_2 \cos(t)$$

$$x_1(0) \Rightarrow 5 = C_1(1) + C_2(0) \rightarrow C_1 = 5$$

$$x_2(0) \Rightarrow -5 = -(5)(0) + C_2(1) \rightarrow C_2 = -5$$

$$(+)\begin{cases} x_1(t) = 5 \cos(t) - 5 \sin(t) \\ x_2(t) = -5 \cos(t) - 5 \sin(t) \end{cases}$$

$$\frac{d}{dt} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} \quad \bar{x}(0) = \begin{bmatrix} 5 \\ -5 \end{bmatrix}$$

$$\boxed{\begin{aligned} \frac{d}{dt} \bar{x} &= A \bar{x} & \bar{x}(0) \\ \bar{x} &= e^{At} \bar{x}(0) \end{aligned}}$$

$$e^{At} = B_1(t)I + B_2(t)A$$

$$\det(A - \lambda I) = 0 \quad \text{ecuación característica.}$$

$$\begin{vmatrix} -\lambda & 1 \\ -1 & -\lambda \end{vmatrix} = 0 \Rightarrow \lambda^2 + 1 = 0 \quad \begin{aligned} \lambda_1 &= i \\ \lambda_2 &= -i \end{aligned}$$

$$\begin{aligned} e^{it} &= B_0 + iB_1 \\ e^{-it} &= B_0 - iB_1 \end{aligned} \Rightarrow \begin{aligned} \cos(t) + i \sin(t) &= B_0 + iB_1 \\ \cos(t) - i \sin(t) &= B_0 - iB_1 \end{aligned}$$

$$\begin{aligned} B_0 &= \cos(t) \\ B_1 &= \sin(t) \end{aligned}$$

$$e^{At} = \cos(t) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \sin(t) \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$e^{At} = \begin{bmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{bmatrix}$$

$$e^{A(0)} = I \quad e^{At} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\frac{d}{dt} e^{At} = A e^{At}$$

$$\frac{d}{dt} e^{At} = \begin{bmatrix} -\sin(t) & \cos(t) \\ -\cos(t) & -\sin(t) \end{bmatrix}$$

$$\begin{aligned} A e^{At} &= \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{bmatrix} \\ &= \begin{bmatrix} -\sin(t) & \cos(t) \\ -\cos(t) & -\sin(t) \end{bmatrix} \end{aligned}$$

$$\bar{x} \Rightarrow \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} = \begin{bmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{bmatrix} \begin{bmatrix} 5 \\ -5 \end{bmatrix}$$

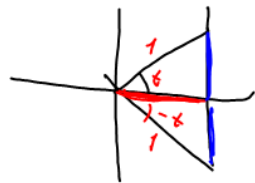
$$\begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} = \begin{bmatrix} 5 \cos(t) - 5 \sin(t) \\ -5 \sin(t) - 5 \cos(t) \end{bmatrix}$$

$$e^{At} \rightarrow e^{A(0)} = I$$

$$\frac{d}{dt} e^{A(t)} = A e^{A(t)}$$

$$\left[e^{A(t)} \right]^{-1} = \left[e^{A(-t)} \right]$$

$$e^{At} = \begin{bmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{bmatrix} \left[e^{A(t)} \right]^{-1} = \begin{bmatrix} \cos(t) & -\sin(t) \\ \sin(t) & \cos(t) \end{bmatrix}$$



$$e^{At} \Rightarrow A$$

$$\begin{bmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{bmatrix} \times \begin{bmatrix} \cos(t) & -\sin(t) \\ \sin(t) & \cos(t) \end{bmatrix}$$

$$e^{At}$$

$$\left[e^{At} \right]^{-1}$$

$$\begin{bmatrix} \cos^2(t) + \sin^2(t) & -\cos(t)\sin(t) + \sin(t)\cos(t) \\ -\cos(t)\sin(t) + \sin(t)\cos(t) & \sin^2(t) + \cos^2(t) \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\frac{d}{dt} \bar{x} = A \bar{x} + \bar{b}(t)$$

$$S(n) \text{ EDO(1) LCC } \text{ NH}$$

$$\frac{dx_1(t)}{dt} = 2x_1(t) + 3x_2(t) + t + 4t^2 + 8e^{2t}$$

$$\frac{dx_2(t)}{dt} = x_1(t) + 4x_2(t) + 3e^{2t} + 4$$

→

$$\frac{d}{dt} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} = \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} + \begin{bmatrix} t + 4t^2 + 8e^{2t} \\ 3e^{2t} + 4 \end{bmatrix}$$

$$\frac{d}{dt} \bar{x} = A \cdot \bar{x} + \bar{b}(t)$$

$$\bar{x} = e^{At} \bar{x}(0) + \int_0^t e^{A(t-z)} \bar{b}(z) dz.$$