

$$\textcircled{1} \quad \frac{dx_1}{dt} = a_{11}x_1 + a_{12}x_2$$

$$\textcircled{2} \quad \frac{dx_2}{dt} = a_{21}x_1 + a_{22}x_2$$

de  $\textcircled{1}$

$$\frac{d}{dt} \left( x_2 = \frac{1}{a_{12}} \left( \frac{dx_1}{dt} - a_{11}x_1 \right) \right)$$

$$\frac{dx_2}{dt} = \frac{1}{a_{12}} \left( \frac{d^2x_1}{dt^2} - a_{11} \frac{dx_1}{dt} \right)$$

Sust en  $\textcircled{2}$

$$\frac{1}{a_{12}} \left( \frac{d^2x_1}{dt^2} - a_{11} \frac{dx_1}{dt} \right) = a_{21}x_1 + a_{22} \left( \frac{1}{a_{12}} \left( \frac{dx_1}{dt} - a_{11}x_1 \right) \right)$$

$$\frac{d^2x_1}{dt^2} - a_{11} \frac{dx_1}{dt} = a_{21}a_{12}x_1 + a_{22} \frac{dx_1}{dt} - a_{22}a_{11}x_1$$

$$\frac{d^2x_1}{dt^2} + (-a_{11} - a_{22}) \frac{dx_1}{dt} + (a_{22}a_{11} - a_{12}a_{21})x_1 = 0$$

$$S(z) \text{ EDO}(1) \text{ LccH} \Rightarrow \text{EDO}(2) \text{ LccH.}$$

MÉTODO DE SUSTITUCION

$$S(n) \text{ EDO}(1) \text{ L} \rightarrow \text{EDO}(n) \text{ L}$$

$$\frac{d^4 y(t)}{dt^4} - 6 \frac{d^3 y(t)}{dt^3} + 4 \frac{d^2 y(t)}{dt^2} - 3 \frac{dy(t)}{dt} + 11 y(t) = 0$$

$$\text{EDO}(4) \text{ LCC H} \longrightarrow S(4) \text{ EDO}(1) \text{ LCC H.}$$

$$y(t) \Rightarrow y_1(t)$$

$$\frac{dy(t)}{dt} \Rightarrow \frac{dy_1(t)}{dt} = y_2(t)$$

$$\frac{d^2 y(t)}{dt^2} \Rightarrow \frac{dy_2(t)}{dt} = y_3(t)$$

$$\frac{d^3 y(t)}{dt^3} \Rightarrow \frac{dy_3(t)}{dt} = y_4(t)$$

$$\frac{d^4 y(t)}{dt^4} \Rightarrow \frac{dy_4(t)}{dt}$$

$$\frac{dy_4(t)}{dt} - 6y_4(t) + 4y_3(t) - 3y_2(t) + 11y_1(t) = 0$$

$$\frac{dy_4(t)}{dt} = -11y_1(t) + 3y_2(t) - 4y_3(t) + 6y_4(t)$$

$$\frac{dy_1(t)}{dt} = (0)y_1(t) + (1)y_2(t) + (0)y_3(t) + (0)y_4(t)$$

$$\frac{dy_2(t)}{dt} = (0)y_1(t) + (0)y_2(t) + (1)y_3(t) + (0)y_4(t)$$

$$\frac{dy_3(t)}{dt} = (0)y_1(t) + (0)y_2(t) + (0)y_3(t) + (1)y_4(t)$$

$$\frac{dy_4(t)}{dt} = (-11)y_1(t) + (3)y_2(t) + (-4)y_3(t) + (6)y_4(t)$$

$$\frac{d}{dt} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -11 & 3 & -4 & 6 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix}$$

$$e^x = 1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots + \frac{x^k}{k!} + \dots$$

$$e = 1 + 1 + \frac{1}{2} + \frac{1}{6} + \dots$$

$$= 2.0 + 0.5 + 0.17 \rightarrow 2.72, \dots$$

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$$e^{At} = I + \frac{A}{1!}t + \frac{A^2}{2!}t^2 + \dots + \frac{A^k}{k!}t^k + \dots$$


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teorema Hamilton-Cayley

$[A]_{n \times n}$  Satisface a su propia ecuación característica

$$\det(A - \lambda I) = 0$$

$$\lambda^n + a_1 \lambda^{n-1} + a_2 \lambda^{n-2} + a_3 \lambda^{n-3} + \dots + a_n = 0$$

$$A^n = -a_1 I - a_2 A - a_3 A^2 - \dots - a_{n-1} A^{n-1} = \begin{bmatrix} 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix} \quad \begin{vmatrix} 2-\lambda & 3 \\ 1 & 4-\lambda \end{vmatrix} = 0$$

$$\det(A - \lambda I) = 0$$

$$(2-\lambda)(4-\lambda) - (1)(3) = 0$$

$$\lambda^2 - 6\lambda + 8 - 3 = 0 \quad \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix} \times \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix} = \begin{bmatrix} 7 & 18 \\ 6 & 19 \end{bmatrix}$$

$$\lambda^2 - 6\lambda + 5 = 0$$

$$\begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix}^2 - 6 \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix} + 5 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 7 & 18 \\ 6 & 19 \end{bmatrix} + \begin{bmatrix} -12 & -18 \\ -6 & -24 \end{bmatrix} + \begin{bmatrix} 5 & 0 \\ 0 & 5 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 7-12+5 & 18-18+0 \\ 6-6+0 & 19-24+5 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$A_{n \times n}$ 

$$e^{At} = B_0(t)I + B_1(t)A + \dots + B_{n-1}(t)A^{n-1}$$

$$\begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix} \quad e^{At} = B_0(t)I + B_1(t)A$$

$$\lambda^2 - 6\lambda + 5 = 0 \quad e^{\lambda_i t} = B_0(t)(1) + B_1(t)\lambda_i$$

$$\lambda_1 = 1$$

$$\lambda_2 = 5$$

$$e^t = B_0(t)(1) + B_1(t)(1)$$

$$e^{5t} = B_0(t)(1) + B_1(t)(5)$$

$$e^{5t} - e^t = 4B_1(t)$$

$$B_1(t) = \frac{1}{4}(e^{5t} - e^t)$$

$$B_0(t) = e^t - B_1(t)$$

$$B_0(t) = e^t - \frac{1}{4}(e^{5t} - e^t)$$

$$B_0(t) = \frac{5e^t}{4} - \frac{e^{5t}}{4}$$

$$e^{At} = \left( \frac{5}{4}e^t - \frac{1}{4}e^{5t} \right) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \left( \frac{1}{4}e^{5t} - \frac{1}{4}e^t \right) \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix}$$

$$e^{At} = \begin{bmatrix} -1+2 & 3 \\ 1 & -1+4 \end{bmatrix} \frac{e^{5t}}{4} + \begin{bmatrix} 5-2 & -3 \\ -1 & 5-4 \end{bmatrix} \frac{e^t}{4}$$

$$e^{At} = \begin{bmatrix} 1 & 3 \\ 1 & 3 \end{bmatrix} \frac{e^{5t}}{4} + \begin{bmatrix} 3 & -3 \\ -1 & 1 \end{bmatrix} \frac{e^t}{4}$$

$$ME := \begin{bmatrix} \frac{3}{4} e^t + \frac{1}{4} e^{5t} & \frac{3}{4} e^{5t} - \frac{3}{4} e^t \\ \frac{1}{4} e^{5t} - \frac{1}{4} e^t & \frac{1}{4} e^t + \frac{3}{4} e^{5t} \end{bmatrix}$$

$$e^{At} = \begin{bmatrix} 1 & 3 \\ 1 & 3 \end{bmatrix} \frac{e^{5t}}{4} + \begin{bmatrix} 3 & -3 \\ -1 & 1 \end{bmatrix} \frac{e^t}{4}$$