

RECORDATORIO:

ENVIAR LAS DOS TAREAS  
AL NUEVO CORREO QUE  
ESTÁ EN LA PÁGINA.

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# SISTEMA DE EDO.

$$\begin{bmatrix} x_1(t) \\ x_2(t) \\ \vdots \\ x_n(t) \end{bmatrix} \quad \begin{aligned} \frac{dx_1}{dt} &= a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \\ \frac{dx_2}{dt} &= a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n \\ \frac{dx_3}{dt} &= a_{31}x_1 + a_{32}x_2 + a_{33}x_3 + \dots + a_{3n}x_n \\ &\vdots \\ \frac{dx_n}{dt} &= a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n \end{aligned}$$

$$\frac{d}{dt} \begin{bmatrix} x_1(t) \\ x_2(t) \\ \vdots \\ x_n(t) \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \\ \vdots \\ x_n(t) \end{bmatrix}$$

$$\frac{d}{dt} \bar{X}(t) = A \times \bar{X}(t)$$

$$\frac{d}{dt} \left( \bar{X}(t) = \left[ e^{At} \right] \bar{X}(0) \right) \quad \frac{d}{dt} e^{At} = A e^{At}$$

$$\frac{d}{dt} \bar{X}(t) = A e^{At} \bar{X}(0)$$

$$A e^{At} \bar{X}(0) = A \left( e^{At} \right) \bar{X}(0)$$

$$\frac{d^4 y(t)}{dt^4} + 8 \frac{d^3 y(t)}{dt^3} - 6 \frac{d^2 y(t)}{dt^2} + 4 \frac{dy(t)}{dt} - 2y(t) = 0$$

EDO(4) Lcc H.

$$y(t) \Rightarrow y_1(t)$$

$$\frac{dy(t)}{dt} \Rightarrow \frac{dy_1(t)}{dt} = y_2(t)$$

$$\frac{d^2 y(t)}{dt^2} \Rightarrow \frac{dy_2(t)}{dt} = y_3(t)$$

$$\frac{d^3 y(t)}{dt^3} \Rightarrow \frac{dy_3(t)}{dt} = y_4(t)$$

$$\frac{d^4 y(t)}{dt^4} \Rightarrow \frac{dy_4(t)}{dt}$$

$$\frac{dy_4(t)}{dt} + 8y_4(t) - 6y_3(t) + 4y_2(t) - 2y_1(t) = 0$$

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$s(4)$  EDO(1) Lcc H.

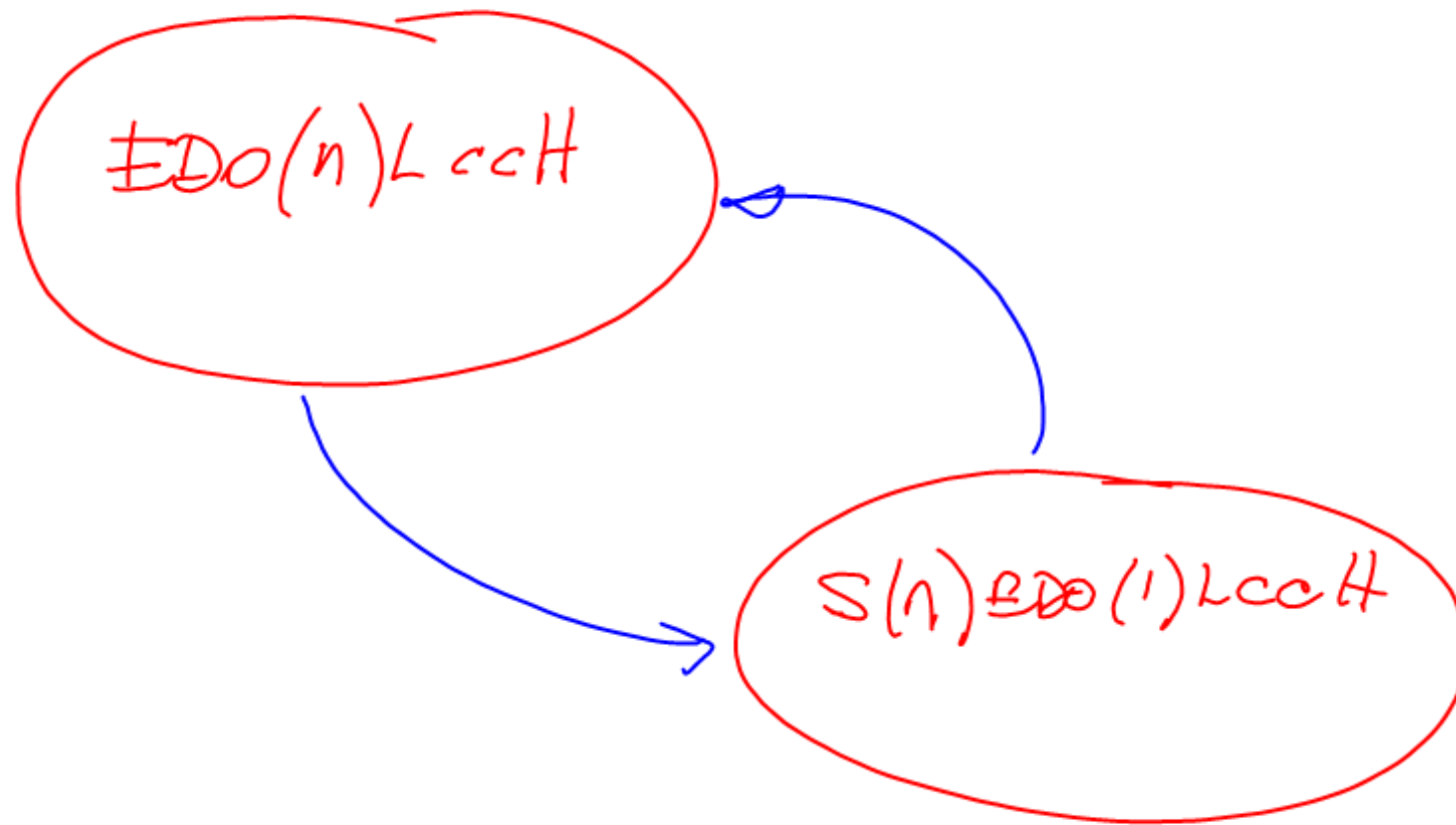
$$\frac{dy_1(t)}{dt} = y_2(t)$$

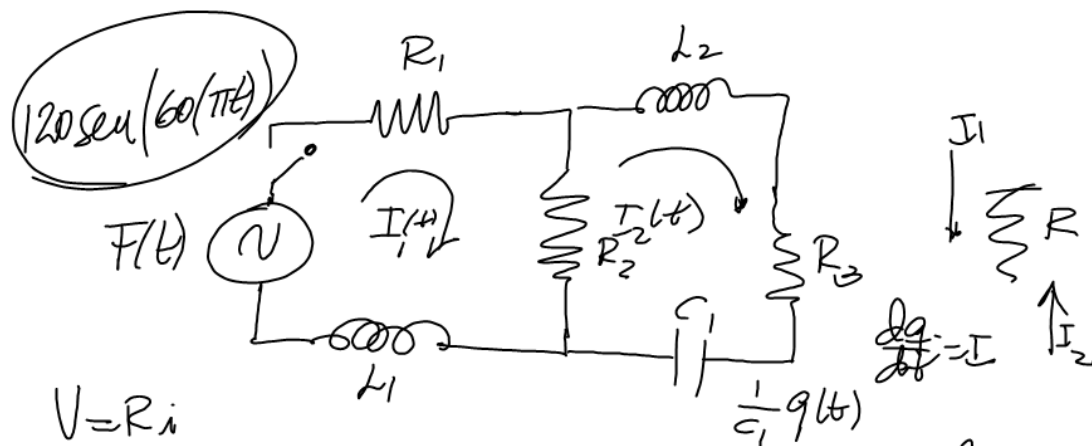
$$\frac{dy_2(t)}{dt} = y_3(t)$$

$$\frac{dy_3(t)}{dt} = y_4(t)$$

$$\frac{dy_4(t)}{dt} = 2y_1(t) - 4y_2(t) + 6y_3(t) - 8y_4(t)$$

$$\frac{d}{dt} \bar{y} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 2 & -4 & 6 & -8 \end{bmatrix} \begin{bmatrix} y_1(t) \\ y_2(t) \\ y_3(t) \\ y_4(t) \end{bmatrix}$$





$$V = Ri$$

$$V = L \frac{di}{dt}$$

$$R_1 I_1(t) + (I_2(t) - I_1(t)) R_2 + L_1 \frac{dI_1(t)}{dt} = F(t)$$

$$R_3 I_2(t) + L_2 \frac{dI_2(t)}{dt} + (I_2(t) - I_1(t)) R_2 = 0$$

$$\left\{ \begin{array}{l} \frac{dI_1(t)}{dt} = \frac{(-R_1 + R_2)}{L_1} I_1(t) - \frac{R_2}{L_1} I_2(t) + \frac{F(t)}{L_1} \\ \frac{dI_2(t)}{dt} = \frac{R_2}{L_2} I_1(t) + \frac{(-R_2 - R_3)}{L_2} I_2(t) \end{array} \right.$$

$$\frac{d}{dt} \begin{bmatrix} I_1(t) \\ I_2(t) \end{bmatrix} = \begin{bmatrix} \frac{-R_1 + R_2}{L_1} & -\frac{R_2}{L_1} \\ \frac{R_2}{L_2} & \frac{-R_2 - R_3}{L_2} \end{bmatrix} \begin{bmatrix} I_1(t) \\ I_2(t) \end{bmatrix} + \begin{bmatrix} \frac{F(t)}{L_1} \\ 0 \end{bmatrix}$$

$$S(z) \in \mathcal{DO}(1) \subset \mathcal{CC} \mathcal{NH}.$$

$$\begin{pmatrix} A \Rightarrow e^{At} \\ n \times n \end{pmatrix} \quad (\text{propios})$$

→ buscar los valores característicos

$$\lambda^n + a_1 \lambda^{n-1} + a_2 \lambda^{n-2} + \dots + a_{n-1} \lambda + a_n = 0$$

A

$\lambda_1 \quad \lambda_2 \quad \lambda_3 \quad \dots \quad \lambda_n$

$$\det(A - \lambda I) = 0$$

$$A_{n \times n}$$

$$e^{At} = B_0(t)I + B_1(t)A + B_2(t)A^2 + \dots + B_{n-1}(t)A^{n-1}$$

$$e^{\lambda_1 t} = B_0(t) + B_1(t)\lambda_1 + B_2(t)\lambda_1^2 + \dots + B_{n-1}(t)\lambda_1^{n-1}$$

$$e^{\lambda_2 t} = B_0(t) + B_1(t)\lambda_2 + B_2(t)\lambda_2^2 + \dots + B_{n-1}(t)\lambda_2^{n-1}$$

$$\vdots$$

$$e^{\lambda_n t} = B_0(t) + B_1(t)\lambda_n + B_2(t)\lambda_n^2 + \dots + B_{n-1}(t)\lambda_n^{n-1}$$

$$A = \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix}$$

$$\det(A - \lambda I) = 0$$

$$\begin{vmatrix} 2-\lambda & 3 \\ 1 & 4-\lambda \end{vmatrix} = 0$$

$$(2-\lambda)(4-\lambda) - 3 = 0$$

$$\lambda^2 - 6\lambda + 5 = 0 \quad \begin{cases} \lambda_1 = 1 \\ \lambda_2 = 5 \end{cases}$$

$$(\lambda - 1)(\lambda - 5) = 0$$

$$2 \times 2 \quad \boxed{e^{At} = B_0(t)I + B_1(t)A} \quad I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad A = \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix}$$

$$\left. \begin{aligned} e^t &= B_0(t) + B_1(t)(1) \\ e^{5t} &= B_0(t) + 5B_1(t) \end{aligned} \right\}$$

$$\frac{e^{5t} - e^t = 4B_1(t)}{e^{5t} - e^t = 4B_1(t)} \quad \rightarrow \quad B_1(t) = \frac{1}{4}(e^{5t} - e^t)$$

$$B_0(t) = e^t - B_1(t)$$

$$B_0(t) = e^t - \frac{1}{4}e^{5t} + \frac{1}{4}e^t$$

$$\boxed{B_0(t) = \frac{5}{4}e^t - \frac{1}{4}e^{5t}}$$

$$e^{At} = \left( \frac{5}{4}e^t - \frac{1}{4}e^{5t} \right) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \left( -\frac{1}{4}e^t + \frac{1}{4}e^{5t} \right) \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix}$$

$$e^{At} = \frac{1}{4} \begin{bmatrix} 5-2 & -3 \\ -1 & 5-4 \end{bmatrix} e^t + \frac{1}{4} \begin{bmatrix} -1+2 & 3 \\ 1 & -1+4 \end{bmatrix} e^{5t}$$

$$\boxed{e^{At} = \frac{1}{4} \begin{bmatrix} 3 & -3 \\ -1 & 1 \end{bmatrix} e^t + \frac{1}{4} \begin{bmatrix} 1 & 3 \\ 1 & 3 \end{bmatrix} e^{5t}}$$





$$V \quad \left[ \begin{array}{c} \text{---} \\ | \\ \text{---} \\ \text{---} \\ | \\ \text{---} \\ | \\ \text{---} \end{array} \right] \quad R_i = V$$

$$\left[ \begin{array}{c} \text{---} \\ | \\ \text{---} \\ | \\ \text{---} \\ | \\ \text{---} \end{array} \right] L \quad L \frac{dI}{dt} = V$$

$$C \quad \begin{array}{c} | \\ \text{---} \\ | \end{array} \quad \begin{array}{c} | \\ \text{---} \\ | \end{array} q \quad \frac{dq}{dt} = I.$$

$$\frac{dx}{dt} = 2x + 3y$$

$$\frac{dy}{dt} = x + 4y$$

$$\frac{d}{dt} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

$$e^{At} \longrightarrow A.$$

$$\frac{d}{dt}e^{At} \longrightarrow Ae^{At} \Big|_{t=0} = A \times I.$$