```
> restart
>
```

PROBLEMA DEL ARCO Y LA FLECHA

```
> EcuaDinamica := -Hooke·s(t) = Masa·diff(s(t), t$2)
```

$$EcuaDinamica := -Hooke\, s(t) = Masa \left(\frac{d^2}{dt^2} s(t) \right) \tag{1}$$

```
> Condicion := s(0) = -392/1000, D(s)(0) = 0
```

$$Condicion := s(0) = -\frac{49}{125}, D(s)(0) = 0 \tag{2}$$

```
> Hooke := (1348/100)/(35/100); Masa := (16/1000)/(981/100);
```

$$Hooke := \frac{1348}{35}$$

$$Masa := \frac{8}{4905} \tag{3}$$

```
> EcuaDinamica; evalf(%, 3)
```

$$-\frac{1348}{35} s(t) = \frac{8}{4905} \frac{d^2}{dt^2} s(t)$$

$$-38.5\, s(t) = 0.00163 \left(\frac{d^2}{dt^2} s(t) \right) \tag{4}$$

```
> Solucion := dsolve({EcuaDinamica, Condicion}); evalf(%, 3); subs(t = 0, rhs(Solucion)); evalf(%, 3)
```

$$Solucion := s(t) = -\frac{49}{125} \cos\left(\frac{3}{14} \sqrt{514262}\, t \right)$$

$$s(t) = -0.392 \cos(153.\, t)$$

$$-\frac{49}{125} \cos(0)$$

$$-0.392 \tag{5}$$

```
> DerSol := diff(Solucion, t); evalf(%, 3); subs(t = 0, rhs(DerSol)); evalf(%, 3)
```

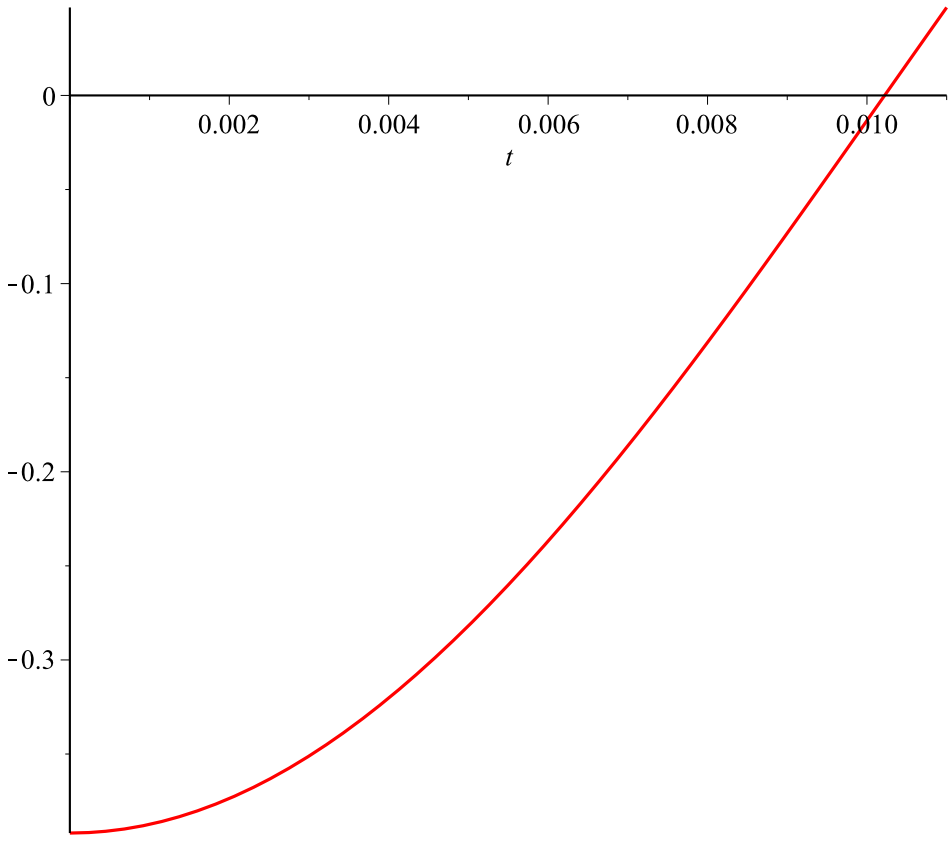
$$DerSol := \frac{d}{dt} s(t) = \frac{21}{250} \sin\left(\frac{3}{14} \sqrt{514262}\, t \right) \sqrt{514262}$$

$$\frac{d}{dt} s(t) = 60.2 \sin(153.\, t)$$

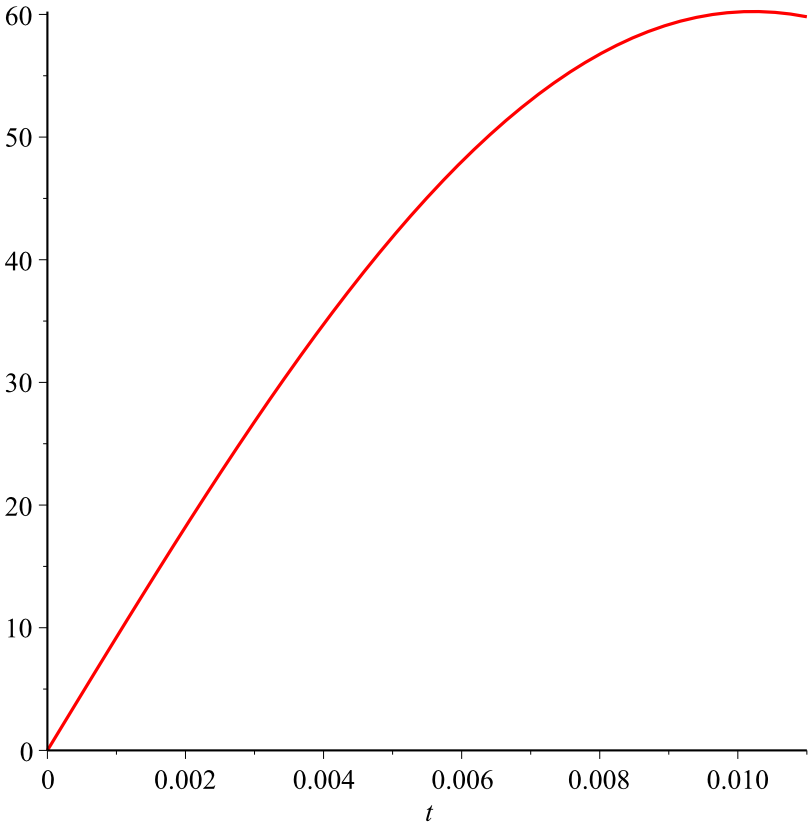
$$\frac{21}{250} \sin(0) \sqrt{514262}$$

$$0. \tag{6}$$

```
> plot(rhs(Solucion), t = 0..0.011)
```




```
> plot(rhs(diff(Solucion, t)), t = 0 ..0.011)
```



> $TiempoEmpuje := solve(rhs(Solucion) = 0) : evalf(\%);$

$$0.01022196621 \quad \textbf{(7)}$$

> $Velocidad := subs(t = TiempoEmpuje, rhs(diff(Solucion, t))); evalf(\%, 4); evalf(\%\%, 4) \cdot 3.6$

$$Velocidad := \frac{21}{250} \sin\left(\frac{1}{2}\pi\right)\sqrt{514262}$$

$$60.24$$

$$216.864 \quad \textbf{(8)}$$

TIRO PARABÓLICO

> $EcuaVertical := diff(y(t), t\$2) = -\frac{981}{100}$

$$EcuaVertical := \frac{d^2}{dt^2} y(t) = -\frac{981}{100} \quad \textbf{(9)}$$

> $EcuaHoriz := diff(x(t), t) = Velocidad \cdot \cos\left(\frac{Pi}{4}\right)$

$$EcuaHoriz := \frac{d}{dt} x(t) = \frac{21}{500}\sqrt{514262}\sqrt{2} \quad \textbf{(10)}$$

> $CondVertical := y(0) = 2, \mathrm{D}(y)(0) = Velocidad \cdot \sin\left(\frac{\mathrm{Pi}}{4}\right)$

$$CondVertical := y(0) = 2, \mathrm{D}(y)(0) = \frac{21}{500}\sqrt{514262}\sqrt{2} \quad (11)$$

> $CondHoriz := x(0) = 5$

$$CondHoriz := x(0) = 5 \quad (12)$$

> $SolVert := dsolve(\{EcuaVertical, CondVertical\}); evalf(\%, 3)$

$$SolVert := y(t) = -\frac{981}{200}t^2 + \frac{21}{500}\sqrt{514262}\sqrt{2}\,t + 2$$

$$y(t) = -4.90\,t^2 + 42.4\,t + 2. \quad (13)$$

> $SolHoriz := dsolve(\{EcuaHoriz, CondHoriz\}); evalf(\%, 3)$

$$SolHoriz := x(t) = \frac{21}{250}\sqrt{257131}\,t + 5$$

$$x(t) = 42.6\,t + 5. \quad (14)$$

> $TiempoVuelo := solve(rhs(SolVert) = 0); evalf(\%, 5)$

$$TiempoVuelo := \frac{14}{1635}\sqrt{257131} - \frac{2}{1635}\sqrt{12871919}, \frac{14}{1635}\sqrt{257131} + \frac{2}{1635}\sqrt{12871919}$$

$$-0.0466, 8.7306 \quad (15)$$

> $DistanciaFinal := subs(t = TiempoVuelo[2], rhs(SolHoriz)); evalf(\%, 6)$

$$DistanciaFinal := \frac{21}{250}\sqrt{257131}\left(\frac{14}{1635}\sqrt{257131} + \frac{2}{1635}\sqrt{12871919}\right) + 5$$

$$376.881 \quad (16)$$

> $TiempoAlturaMax := solve(rhs(diff(SolVert, t)) = 0); evalf(\%)$

$$TiempoAlturaMax := \frac{7}{1635}\sqrt{514262}\sqrt{2}$$

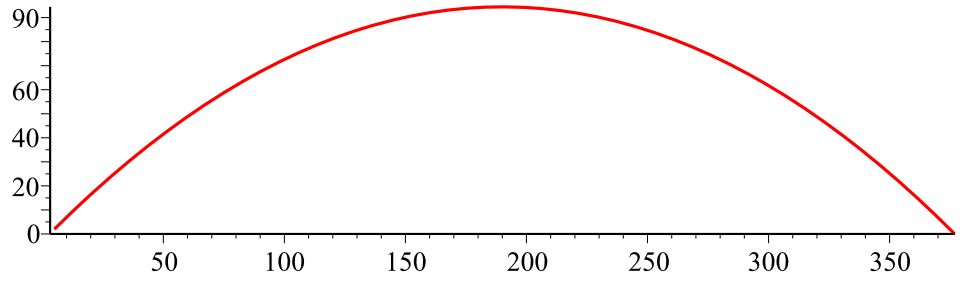
$$4.341976796 \quad (17)$$

> $AlturaMax := subs(t = TiempoAlturaMax, rhs(SolVert)); evalf(\%)$

$$AlturaMax := \frac{118091}{1250}$$

$$94.47280000 \quad (18)$$

> $plot([rhs(SolHoriz), rhs(SolVert), t = 0..TiempoVuelo[2]], scaling = CONSTRAINED)$


90
60
40
20
0
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300
350