

```

> restart
> Sistema1 := diff(x[1](t), t) = 2·x[1](t) + 3·x[2](t), diff(x[2](t), t) = x[1](t) + 4·x[2](t) :
Sistema1[1]; Sistema1[2]

$$\frac{d}{dt} x_1(t) = 2 x_1(t) + 3 x_2(t)$$


$$\frac{d}{dt} x_2(t) = x_1(t) + 4 x_2(t) \quad (1)$$


```

```

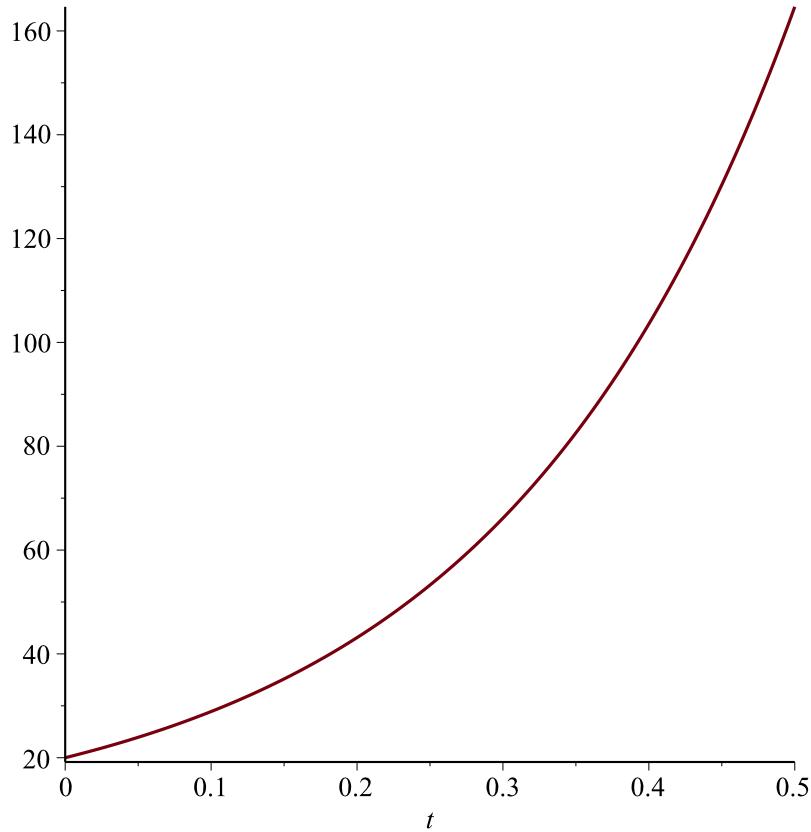
> Cond := x[1](0) = 20, x[2](0) = 10
Cond := x1(0) = 20, x2(0) = 10 \quad (2)

```

```

> Solucion1 := dsolve( {Sistema1, Cond}, {x[1](t), x[2](t)} ) :
> plot(rhs(Solucion1[1]), t=0..0.5)

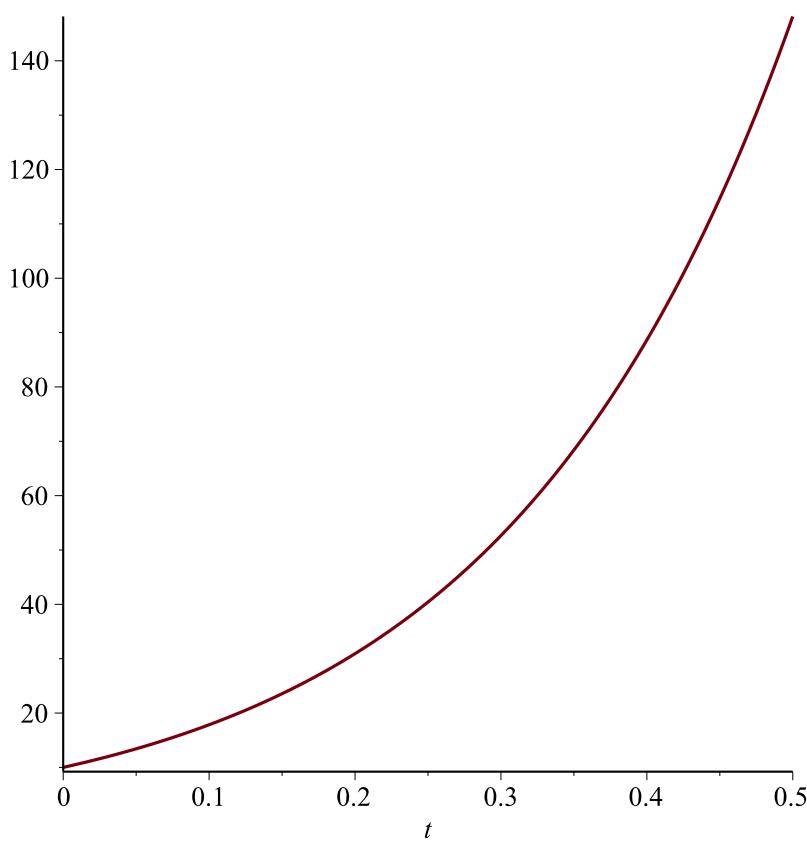
```



```

> plot(rhs(Solucion1[2]), t=0..0.5)

```



> *SolucionI[1]; SolucionI[2]*

$$x_1(t) = \frac{25}{2} e^{5t} + \frac{15}{2} e^t$$

$$x_2(t) = \frac{25}{2} e^{5t} - \frac{5}{2} e^t$$

(3)