

```
> restart
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```
> Ecua := diff(y(t), t$3) + diff(y(t), t$2) + diff(y(t), t) + y(t) = 4*exp(2*t)
```

$$Ecua := \frac{d^3}{dt^3} y(t) + \frac{d^2}{dt^2} y(t) + \frac{d}{dt} y(t) + y(t) = 4 e^{2t} \quad (1)$$

```
> Cond := y(0) = 1, D(y)(0) = 2, D(D(y))(0) = 3
```

$$Cond := y(0) = 1, D(y)(0) = 2, D^{(2)}(y)(0) = 3 \quad (2)$$

```
> with(inttrans) :
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```
> EcuaTrans := subs(Cond, laplace(Ecua, t, s))
```

$$EcuaTrans := s^3 \text{laplace}(y(t), t, s) - 6 - 3s - s^2 + s^2 \text{laplace}(y(t), t, s) + s \text{laplace}(y(t), t, s) + \text{laplace}(y(t), t, s) = \frac{4}{s-2} \quad (3)$$

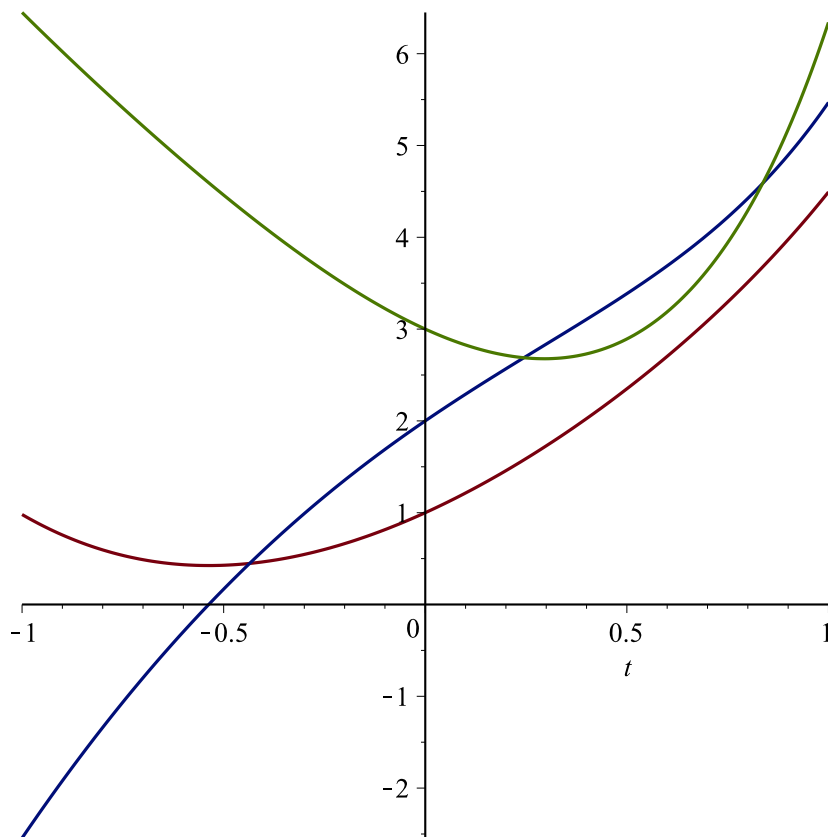
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> SolTrans := isolate(EcuaTrans, laplace(y(t), t, s))
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$$SolTrans := \text{laplace}(y(t), t, s) = \frac{\frac{4}{s-2} + s^2 + 3s + 6}{s^3 + s^2 + s + 1} \quad (4)$$

```
> SolPart := invlaplace(SolTrans, s, t)
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$$SolPart := y(t) = \frac{4}{15} e^{2t} - \frac{3}{5} \cos(t) + \frac{14}{5} \sin(t) + \frac{4}{3} e^{-t} \quad (5)$$

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> plot([rhs(SolPart), rhs(diff(SolPart, t)), rhs(diff(SolPart, t$2))], t=-1..1)
```



> restart

> Sist := diff(y[1](t), t) = y[2](t), diff(y[2](t), t) = y[3](t), diff(y[3](t), t) = -y[1](t) - y[2](t) - y[3](t) + 4·exp(2·t) : Sist[1]; Sist[2]; Sist[3]

$$\frac{d}{dt} y_1(t) = y_2(t)$$

$$\frac{d}{dt} y_2(t) = y_3(t)$$

$$\frac{d}{dt} y_3(t) = -y_1(t) - y_2(t) - y_3(t) + 4e^{2t} \quad (6)$$

> Cond := y[1](0) = 1, y[2](0) = 2, y[3](0) = 3

$$Cond := y_1(0) = 1, y_2(0) = 2, y_3(0) = 3 \quad (7)$$

> AA := array([[0, 1, 0], [0, 0, 1], [-1, -1, -1]])

$$AA := \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -1 & -1 \end{bmatrix} \quad (8)$$

> BB := array([0, 0, 4·exp(2·t)])

(9)

$$BB := \begin{bmatrix} 0 & 0 & 4 e^{2t} \end{bmatrix} \quad (9)$$

> Cond := array([1, 2, 3])

$$Cond := \begin{bmatrix} 1 & 2 & 3 \end{bmatrix} \quad (10)$$

> with(linalg) :

> MatExp := exponential(AA, t)

$$MatExp := \begin{bmatrix} \frac{1}{2} e^{-t} + \frac{1}{2} \cos(t) + \frac{1}{2} \sin(t) & \sin(t) & \frac{1}{2} \sin(t) - \frac{1}{2} \cos(t) + \frac{1}{2} e^{-t} \\ -\frac{1}{2} \sin(t) + \frac{1}{2} \cos(t) - \frac{1}{2} e^{-t} & \cos(t) & \frac{1}{2} \cos(t) - \frac{1}{2} e^{-t} + \frac{1}{2} \sin(t) \\ -\frac{1}{2} \cos(t) + \frac{1}{2} e^{-t} - \frac{1}{2} \sin(t) & -\sin(t) & \frac{1}{2} e^{-t} - \frac{1}{2} \sin(t) + \frac{1}{2} \cos(t) \end{bmatrix} \quad (11)$$

> CompUno := map(rcurry(eval, t='0'), MatExp)

$$CompUno := \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad (12)$$

> DerMatExp := map(diff, MatExp, t)

DerMatExp := (13)

$$\begin{bmatrix} -\frac{1}{2} \sin(t) + \frac{1}{2} \cos(t) - \frac{1}{2} e^{-t} & \cos(t) & \frac{1}{2} \cos(t) - \frac{1}{2} e^{-t} + \frac{1}{2} \sin(t) \\ -\frac{1}{2} \cos(t) + \frac{1}{2} e^{-t} - \frac{1}{2} \sin(t) & -\sin(t) & \frac{1}{2} e^{-t} - \frac{1}{2} \sin(t) + \frac{1}{2} \cos(t) \\ \frac{1}{2} \sin(t) - \frac{1}{2} e^{-t} - \frac{1}{2} \cos(t) & -\cos(t) & -\frac{1}{2} e^{-t} - \frac{1}{2} \cos(t) - \frac{1}{2} \sin(t) \end{bmatrix}$$

> CompDos := evalm(DerMatExp - evalm(AA &* MatExp))

$$CompDos := \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad (14)$$

> SolHom := evalm(MatExp &* Cond) : SolHom[1]; SolHom[2]; SolHom[3]

$$\begin{aligned} & 2 e^{-t} - \cos(t) + 4 \sin(t) \\ & \sin(t) + 4 \cos(t) - 2 e^{-t} \\ & \cos(t) + 2 e^{-t} - 4 \sin(t) \end{aligned} \quad (15)$$

> MatExpTau := map(rcurry(eval, t='t - tau'), MatExp) : MatExpTau[2, 2]

$$\cos(t - \tau) \quad (16)$$

> BBtau := map(rcurry(eval, t='tau'), BB)

$$BBtau := \begin{bmatrix} 0 & 0 & 4 e^{2\tau} \end{bmatrix} \quad (17)$$

> ProdTau := evalm(MatExpTau &* BBtau) : ProdTau[1]; ProdTau[2]; ProdTau[3]

$$\begin{aligned}
& 4 \left(\frac{1}{2} \sin(t-\tau) - \frac{1}{2} \cos(t-\tau) + \frac{1}{2} e^{-t+\tau} \right) e^{2\tau} \\
& 4 \left(\frac{1}{2} \cos(t-\tau) - \frac{1}{2} e^{-t+\tau} + \frac{1}{2} \sin(t-\tau) \right) e^{2\tau} \\
& 4 \left(\frac{1}{2} e^{-t+\tau} - \frac{1}{2} \sin(t-\tau) + \frac{1}{2} \cos(t-\tau) \right) e^{2\tau}
\end{aligned} \tag{18}$$

> *SolNoHom* := *simplify*(*map*(*int*, *ProdTau*, tau = 0 .. t)) : *SolNoHom*[1]; *SolNoHom*[2];
SolNoHom[3]

$$\begin{aligned}
& \frac{2}{15} e^{-t} (-9 \sin(t) e^t + 3 \cos(t) e^t + 2 e^{3t} - 5) \\
& \frac{2}{15} e^{-t} (4 e^{3t} - 3 \sin(t) e^t - 9 \cos(t) e^t + 5) \\
& \frac{2}{15} e^{-t} (8 e^{3t} + 9 \sin(t) e^t - 3 \cos(t) e^t - 5)
\end{aligned} \tag{19}$$

> *CompTres* := *map*(*rcurry*(*eval*, t=0), *SolNoHom*)

$$\textit{CompTres} := \begin{bmatrix} 0 & 0 & 0 \end{bmatrix} \tag{20}$$

> *SolPart*[1] := *y*[1](t) = *simplify*(*SolHom*[1] + *SolNoHom*[1])

$$\textit{SolPart}_1 := y_1(t) = \frac{14}{5} \sin(t) - \frac{3}{5} \cos(t) + \frac{4}{15} e^{2t} + \frac{4}{3} e^{-t} \tag{21}$$

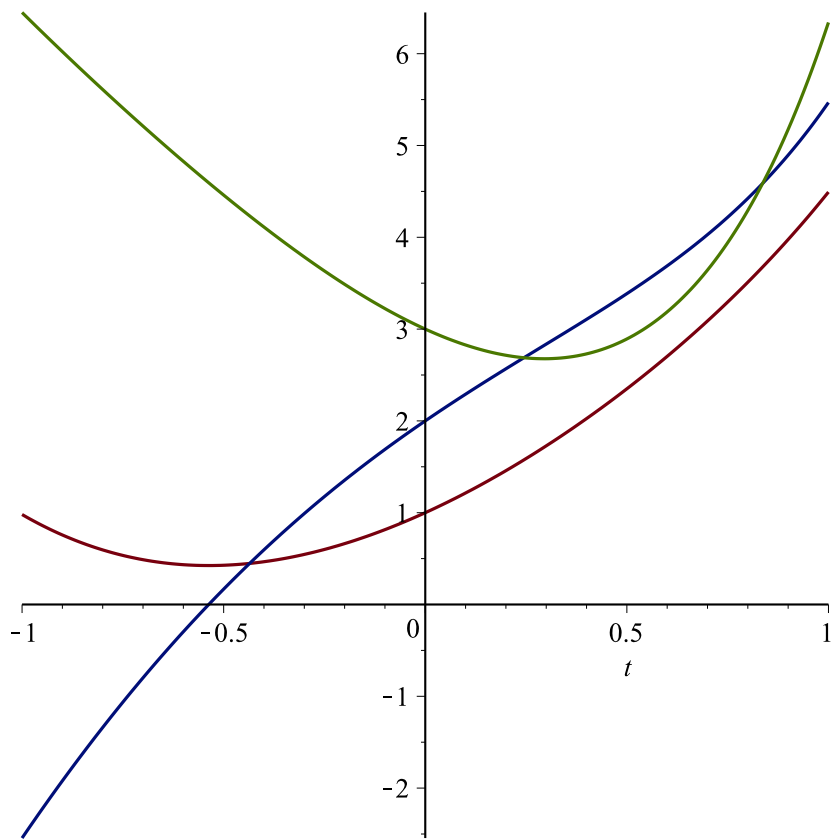
> *SolPart*[2] := *y*[2](t) = *simplify*(*SolHom*[2] + *SolNoHom*[2])

$$\textit{SolPart}_2 := y_2(t) = \frac{3}{5} \sin(t) + \frac{14}{5} \cos(t) + \frac{8}{15} e^{2t} - \frac{4}{3} e^{-t} \tag{22}$$

> *SolPart*[3] := *y*[3](t) = *simplify*(*SolHom*[3] + *SolNoHom*[3])

$$\textit{SolPart}_3 := y_3(t) = -\frac{14}{5} \sin(t) + \frac{3}{5} \cos(t) + \frac{16}{15} e^{2t} + \frac{4}{3} e^{-t} \tag{23}$$

> *plot*([*rhs*(*SolPart*[1]), *rhs*(*SolPart*[2]), *rhs*(*SolPart*[3])], t = -1 .. 1)



> `plot([rhs(SolPart[1]), rhs(SolPart[2]), rhs(SolPart[3])], t = 0..10)`

