

```
> restart
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>
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PROBLEMA DEL ARCO Y LA FLECHA

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> EcuaDinamica := -Hooke·s(t) = Masa·diff(s(t), t$2)
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$$EcuaDinamica := -Hooke s(t) = Masa \left(\frac{d^2}{dt^2} s(t) \right) \quad (1)$$

```
> Condicion := s(0) = -\frac{392}{1000}, D(s)(0) = 0
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$$Condicion := s(0) = -\frac{49}{125}, D(s)(0) = 0 \quad (2)$$

```
> Hooke := \frac{\left(\frac{1348}{100}\right)}{\frac{35}{100}}; Masa := \frac{\left(\frac{16}{1000}\right)}{\frac{981}{100}};
```

$$Hooke := \frac{1348}{35}$$

$$Masa := \frac{8}{4905} \quad (3)$$

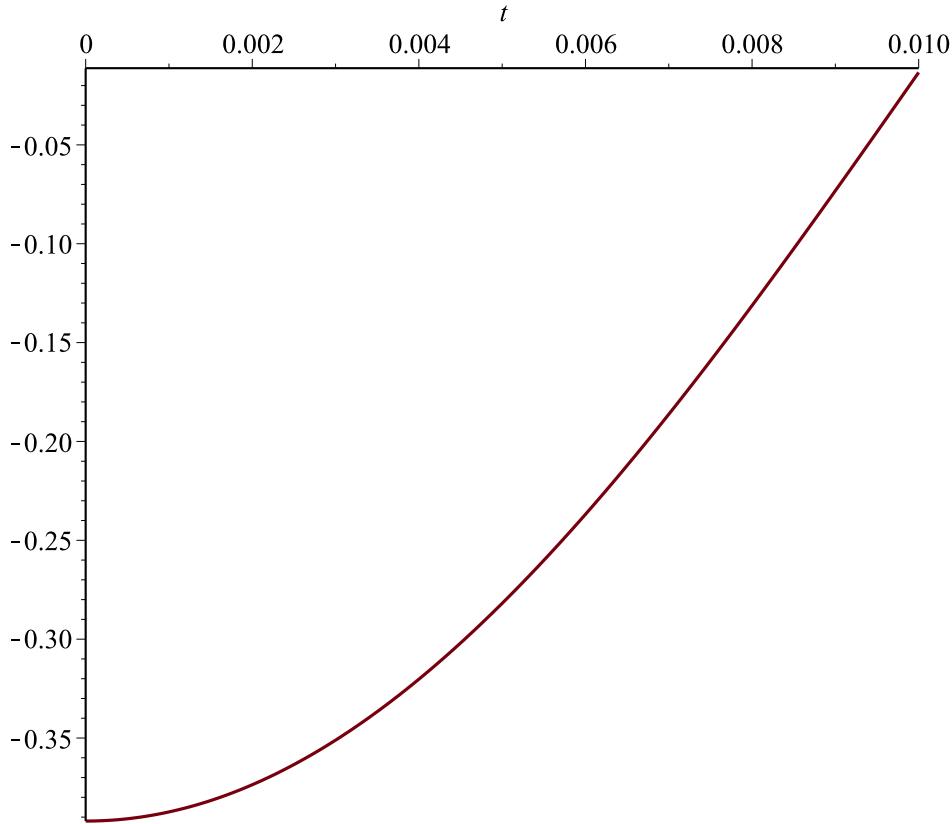
```
> EcuaDinamica
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$$-\frac{1348}{35} s(t) = \frac{8}{4905} \frac{d^2}{dt^2} s(t) \quad (4)$$

```
> Solucion := dsolve( {EcuaDinamica, Condicion})
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$$Solucion := s(t) = -\frac{49}{125} \cos\left(\frac{3}{14} \sqrt{514262} t\right) \quad (5)$$

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> plot(rhs(Solucion), t=0 .. 0.01)
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> $TiempoEmpuje := solve(rhs(Solucion) = 0) : evalf(\%);$
 $\quad \quad \quad 0.01022196621$ (6)

> $Velocidad := subs(t = TiempoEmpuje, rhs(diff(Solucion, t))) ; evalf(\%) ; evalf(\%)\cdot 3.6$
 $\quad \quad \quad Velocidad := \frac{21}{250} \sin\left(\frac{1}{2} \pi\right) \sqrt{514262}$
 $\quad \quad \quad 60.23813304$
 $\quad \quad \quad 216.8572789$ (7)

> $EcuaVertical := diff(y(t), t\$2) = -\frac{981}{100}$
 $\quad \quad \quad EcuaVertical := \frac{d^2}{dt^2} y(t) = -\frac{981}{100}$ (8)

> $EcuaHoriz := diff(x(t), t) = Velocidad \cdot \cos\left(\frac{\pi}{4}\right)$
 $\quad \quad \quad EcuaHoriz := \frac{d}{dt} x(t) = \frac{21}{500} \sqrt{514262} \sqrt{2}$ (9)

> $CondVertical := y(0) = 2, D(y)(0) = Velocidad \cdot \sin\left(\frac{\pi}{4}\right)$

$$CondVertical := y(0) = 2, D(y)(0) = \frac{21}{500} \sqrt{514262} \sqrt{2} \quad (10)$$

> $CondHoriz := x(0) = 5$

$$CondHoriz := x(0) = 5 \quad (11)$$

> $SolVert := dsolve(\{EcuaVertical, CondVertical\})$

$$SolVert := y(t) = -\frac{981}{200} t^2 + \frac{21}{500} \sqrt{514262} \sqrt{2} t + 2 \quad (12)$$

> $SolHoriz := dsolve(\{EcuaHoriz, CondHoriz\})$

$$SolHoriz := x(t) = \frac{21}{250} \sqrt{257131} t + 5 \quad (13)$$

> $TiempoVuelo := solve(rhs(SolVert) = 0); evalf(\%)$

$$\begin{aligned} TiempoVuelo := & \frac{14}{1635} \sqrt{257131} - \frac{2}{1635} \sqrt{12871919}, \frac{14}{1635} \sqrt{257131} \\ & + \frac{2}{1635} \sqrt{12871919} \\ & -0.046702924, 8.730656514 \end{aligned} \quad (14)$$

> $DistanciaFinal := subs(t = TiempoVuelo[2], rhs(SolHoriz)); evalf(\%)$

$$\begin{aligned} DistanciaFinal := & \frac{21}{250} \sqrt{257131} \left(\frac{14}{1635} \sqrt{257131} + \frac{2}{1635} \sqrt{12871919} \right) + 5 \\ & 376.8805014 \end{aligned} \quad (15)$$

> $TiempoAlturaMax := solve(rhs(diff(SolVert, t)) = 0); evalf(\%)$

$$\begin{aligned} TiempoAlturaMax := & \frac{7}{1635} \sqrt{514262} \sqrt{2} \\ & 4.341976796 \end{aligned} \quad (16)$$

> $AlturaMax := subs(t = TiempoAlturaMax, rhs(SolVert)); evalf(\%)$

$$\begin{aligned} AlturaMax := & \frac{118091}{1250} \\ & 94.47280000 \end{aligned} \quad (17)$$

> $plot([rhs(SolHoriz), rhs(SolVert), t = 0 .. TiempoVuelo[2]], scaling = CONSTRAINED)$

