

```

> restart
> Sist := diff(x[1](t), t) = 3·x[1](t) + 4·x[2](t), diff(x[2](t), t) = 6·x[1](t) + 8·x[2](t) :
   Sist[1]; Sist[2]
      
$$\frac{d}{dt} x_1(t) = 3 x_1(t) + 4 x_2(t)$$

      
$$\frac{d}{dt} x_2(t) = 6 x_1(t) + 8 x_2(t) \quad (1)$$


> Sol := dsolve({Sist}) : Sol[1]; Sol[2]
      
$$x_1(t) = _C1 + _C2 e^{11t}$$

      
$$x_2(t) = 2 _C2 e^{11t} - \frac{3}{4} _C1 \quad (2)$$


> AA := array([[3, 4], [6, 8]])
      
$$AA := \begin{bmatrix} 3 & 4 \\ 6 & 8 \end{bmatrix} \quad (3)$$


> with(linalg):
> MatExp := exponential(AA, t)
      
$$MatExp := \begin{bmatrix} \frac{8}{11} + \frac{3}{11} e^{11t} & \frac{4}{11} e^{11t} - \frac{4}{11} \\ \frac{6}{11} e^{11t} - \frac{6}{11} & \frac{3}{11} + \frac{8}{11} e^{11t} \end{bmatrix} \quad (4)$$


> det(AA)
      0 \quad (5)

> Xzero := array([_C10, _C20])
      
$$Xzero := \begin{bmatrix} _C10 & _C20 \end{bmatrix} \quad (6)$$


> SolGral := evalm(MatExp &* Xzero) : SolGral[1]; SolGral[2]
      
$$\left( \frac{8}{11} + \frac{3}{11} e^{11t} \right) _C10 + \left( \frac{4}{11} e^{11t} - \frac{4}{11} \right) _C20$$

      
$$\left( \frac{6}{11} e^{11t} - \frac{6}{11} \right) _C10 + \left( \frac{3}{11} + \frac{8}{11} e^{11t} \right) _C20 \quad (7)$$


> Sol[1]; Sol[2]
      
$$x_1(t) = _C1 + _C2 e^{11t}$$

      
$$x_2(t) = 2 _C2 e^{11t} - \frac{3}{4} _C1 \quad (8)$$


> restart
> SistNoHom := diff(x[1](t), t) = 2·x[1](t) + 3·x[2](t) + exp(2·t) + t^2, diff(x[2](t), t)
   = x[1](t) + 4·x[2](t) + cos(2·t) : SistNoHom[1]; SistNoHom[2];
      
$$\frac{d}{dt} x_1(t) = 2 x_1(t) + 3 x_2(t) + e^{2t} + t^2$$

      
$$\frac{d}{dt} x_2(t) = x_1(t) + 4 x_2(t) + \cos(2t) \quad (9)$$


> CondIni := x[1](0) = -3, x[2](0) = 5

```

$$CondIni := x_1(0) = -3, x_2(0) = 5 \quad (10)$$

> $AA := \text{array}([[2, 3], [1, 4]])$

$$AA := \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix} \quad (11)$$

> $Xzero := \text{array}([-3, 5])$

$$Xzero := \begin{bmatrix} -3 & 5 \end{bmatrix} \quad (12)$$

> $BB := \text{array}([\mathrm{e}^{2t} + t^2, \cos(2t)])$

$$BB := \begin{bmatrix} \mathrm{e}^{2t} + t^2 & \cos(2t) \end{bmatrix} \quad (13)$$

> $\text{with(linalg)} :$

> $\text{MatExp} := \text{exponential}(AA, t)$

$$\text{MatExp} := \begin{bmatrix} \frac{3}{4} \mathrm{e}^t + \frac{1}{4} \mathrm{e}^{5t} & \frac{3}{4} \mathrm{e}^{5t} - \frac{3}{4} \mathrm{e}^t \\ \frac{1}{4} \mathrm{e}^{5t} - \frac{1}{4} \mathrm{e}^t & \frac{1}{4} \mathrm{e}^t + \frac{3}{4} \mathrm{e}^{5t} \end{bmatrix} \quad (14)$$

> $SolHom := \text{evalm}(\text{MatExp} \&* Xzero) : SolHom[1]; SolHom[2]$

$$\begin{aligned} & -6 \mathrm{e}^t + 3 \mathrm{e}^{5t} \\ & 3 \mathrm{e}^{5t} + 2 \mathrm{e}^t \end{aligned} \quad (15)$$

> $\text{MatExpTau} := \text{map}(\text{rcurry}(\text{eval}, t = t - \tau), \text{MatExp})$

$$\text{MatExpTau} := \begin{bmatrix} \frac{3}{4} \mathrm{e}^{t-\tau} + \frac{1}{4} \mathrm{e}^{5t-5\tau} & \frac{3}{4} \mathrm{e}^{5t-5\tau} - \frac{3}{4} \mathrm{e}^{t-\tau} \\ \frac{1}{4} \mathrm{e}^{5t-5\tau} - \frac{1}{4} \mathrm{e}^{t-\tau} & \frac{1}{4} \mathrm{e}^{t-\tau} + \frac{3}{4} \mathrm{e}^{5t-5\tau} \end{bmatrix} \quad (16)$$

> $\text{evalm}(BB)$

$$\begin{bmatrix} \mathrm{e}^{2t} + t^2 & \cos(2t) \end{bmatrix} \quad (17)$$

> $Btau := \text{map}(\text{rcurry}(\text{eval}, t = \tau), BB)$

$$Btau := \begin{bmatrix} \mathrm{e}^{2\tau} + \tau^2 & \cos(2\tau) \end{bmatrix} \quad (18)$$

> $\text{ProdTau} := \text{evalm}(\text{MatExpTau} \&* Btau) : ProdTau[1]; ProdTau[2]$

$$\begin{aligned} & \left(\frac{3}{4} \mathrm{e}^{t-\tau} + \frac{1}{4} \mathrm{e}^{5t-5\tau} \right) (\mathrm{e}^{2\tau} + \tau^2) + \left(\frac{3}{4} \mathrm{e}^{5t-5\tau} - \frac{3}{4} \mathrm{e}^{t-\tau} \right) \cos(2\tau) \\ & \left(\frac{1}{4} \mathrm{e}^{5t-5\tau} - \frac{1}{4} \mathrm{e}^{t-\tau} \right) (\mathrm{e}^{2\tau} + \tau^2) + \left(\frac{1}{4} \mathrm{e}^{t-\tau} + \frac{3}{4} \mathrm{e}^{5t-5\tau} \right) \cos(2\tau) \end{aligned} \quad (19)$$

> $\text{SolNoHom} := \text{map}(\text{int}, \text{ProdTau}, \tau = 0 .. t) : SolNoHom[1]; SolNoHom[2];$

$$\begin{aligned} & \frac{2356}{10875} \mathrm{e}^{5t} + \frac{3}{5} \mathrm{e}^t + \frac{6}{145} \cos(t)^2 + \frac{2}{3} \mathrm{e}^{2t} - \frac{72}{145} \cos(t) \sin(t) - \frac{38}{25} t - \frac{4}{5} t^2 - \frac{5527}{3625} \\ & \frac{2356}{10875} \mathrm{e}^{5t} - \frac{1}{5} \mathrm{e}^t - \frac{52}{145} \cos(t)^2 - \frac{1}{3} \mathrm{e}^{2t} + \frac{44}{145} \cos(t) \sin(t) + \frac{12}{25} t + \frac{1}{5} t^2 + \frac{2448}{3625} \end{aligned} \quad (20)$$

> $\text{SolFinal} := \text{evalm}(\text{SolHom} + \text{SolNoHom}) : x[1](t) = \text{simplify}(\text{SolFinal}[1]); x[2](t) = \text{simplify}(\text{SolFinal}[2])$

$$\begin{aligned}
x_1(t) &= -\frac{27}{5} e^t + \frac{34981}{10875} e^{5t} + \frac{6}{145} \cos(t)^2 + \frac{2}{3} e^{2t} - \frac{72}{145} \cos(t) \sin(t) - \frac{38}{25} t - \frac{4}{5} t^2 \\
&\quad - \frac{5527}{3625} \\
x_2(t) &= \frac{34981}{10875} e^{5t} + \frac{9}{5} e^t - \frac{52}{145} \cos(t)^2 - \frac{1}{3} e^{2t} + \frac{44}{145} \cos(t) \sin(t) + \frac{12}{25} t + \frac{1}{5} t^2 \\
&\quad + \frac{2448}{3625}
\end{aligned} \tag{21}$$

$$\begin{aligned}
> x[1](t) &= \text{evalf}(\text{SolFinal}[1], 2); x[2](t) = \text{evalf}(\text{SolFinal}[2], 2) \\
x_1(t) &= -5.4 e^t + 3.2 e^{5t} + 0.041 \cos(t)^2 + 0.67 e^{2t} - 0.50 \cos(t) \sin(t) - 1.5 t - 0.80 t^2 - 1.5 \\
x_2(t) &= 3.2 e^{5t} + 1.8 e^t - 0.36 \cos(t)^2 - 0.33 e^{2t} + 0.30 \cos(t) \sin(t) + 0.48 t + 0.20 t^2 + 0.68
\end{aligned} \tag{22}$$

> *SistNoHom*[1]

$$\frac{d}{dt} x_1(t) = 2 x_1(t) + 3 x_2(t) + e^{2t} + t^2 \tag{23}$$

$$\begin{aligned}
> \text{ComprobarUno} &:= \text{simplify}(\text{eval}(\text{subs}(x[1](t) = \text{SolFinal}[1], x[2](t) = \text{SolFinal}[2], \\
&\quad \text{lhs}(\text{SistNoHom}[1]) - \text{rhs}(\text{SistNoHom}[1]) = 0))) \\
&\quad \text{ComprobarUno} := 0 = 0
\end{aligned} \tag{24}$$

> *SistNoHom*[2]

$$\frac{d}{dt} x_2(t) = x_1(t) + 4 x_2(t) + \cos(2t) \tag{25}$$

$$\begin{aligned}
> \text{ComprobarDos} &:= \text{simplify}(\text{eval}(\text{subs}(x[1](t) = \text{SolFinal}[1], x[2](t) = \text{SolFinal}[2], \\
&\quad \text{lhs}(\text{SistNoHom}[2]) - \text{rhs}(\text{SistNoHom}[2]) = 0))) \\
&\quad \text{ComprobarDos} := 0 = 0
\end{aligned} \tag{26}$$

>