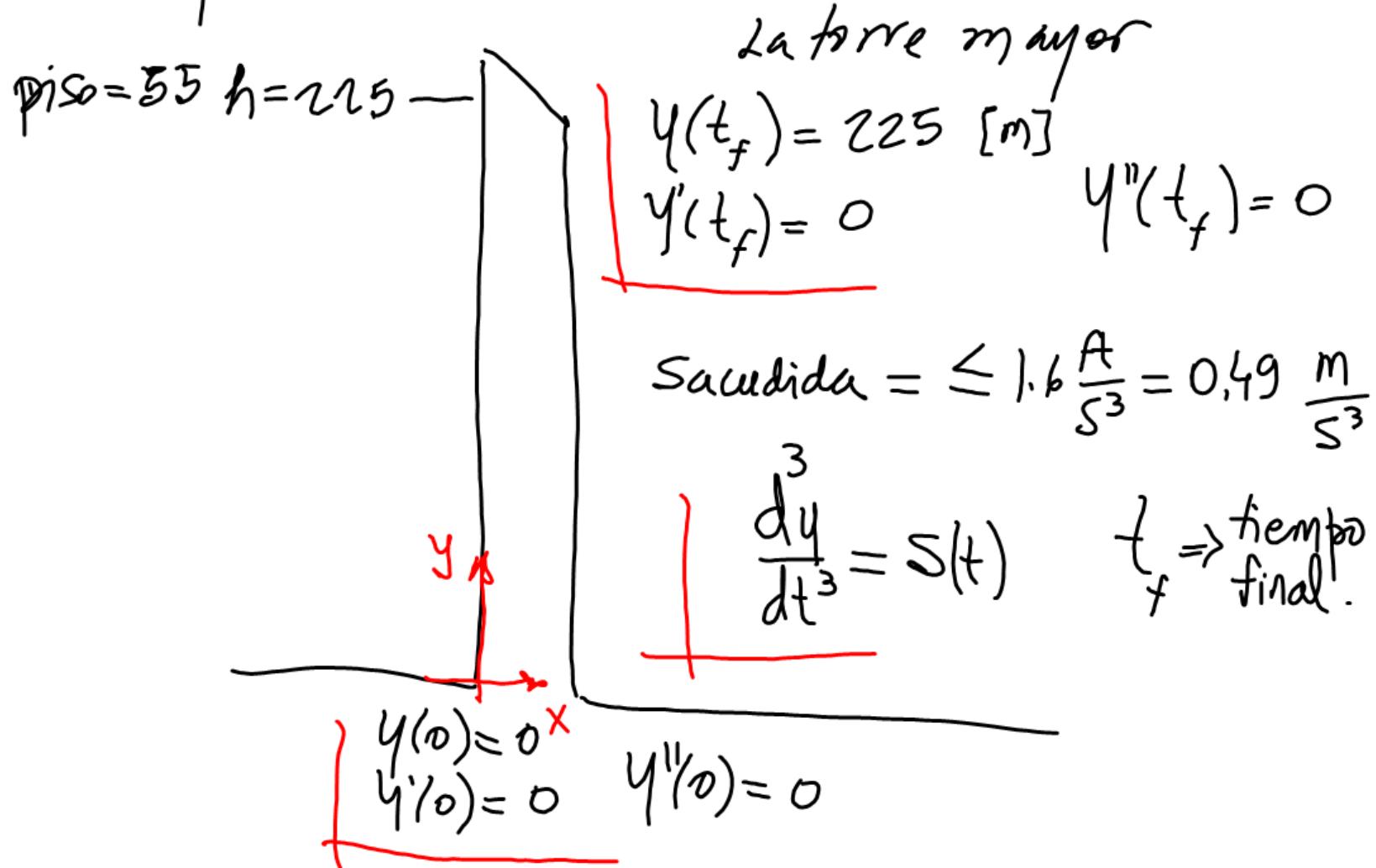


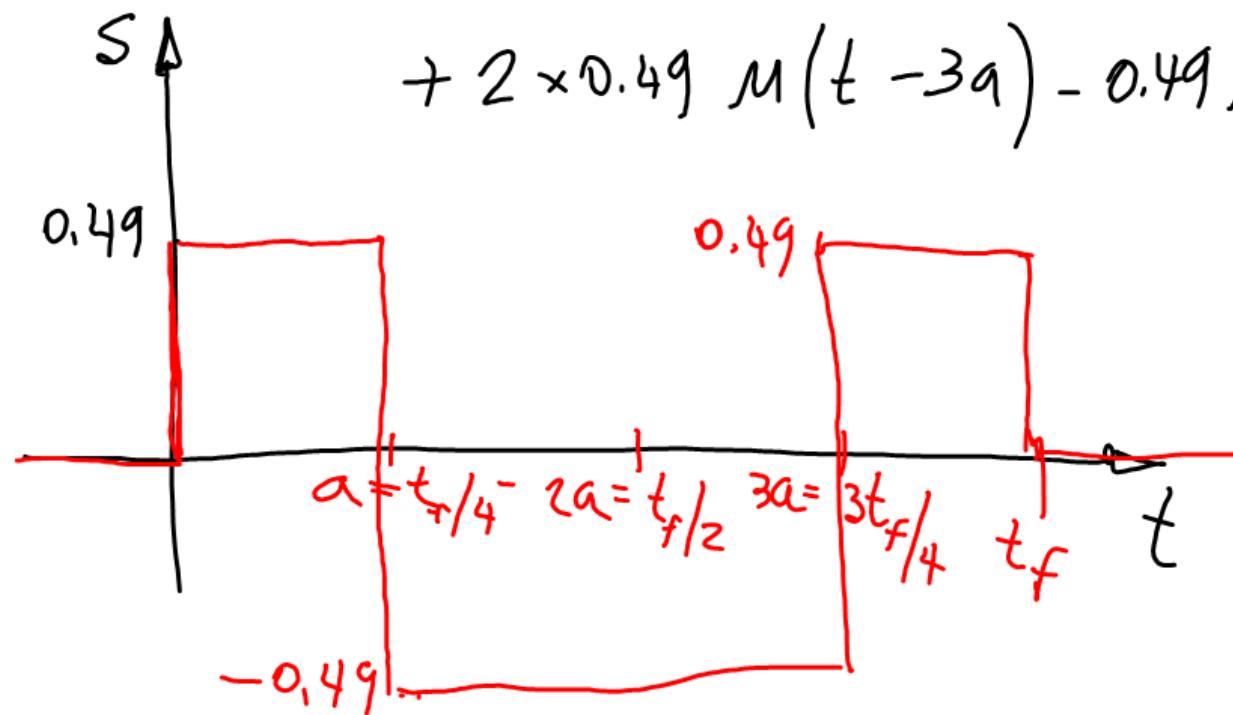
Aplicación: Transformada de Laplace.

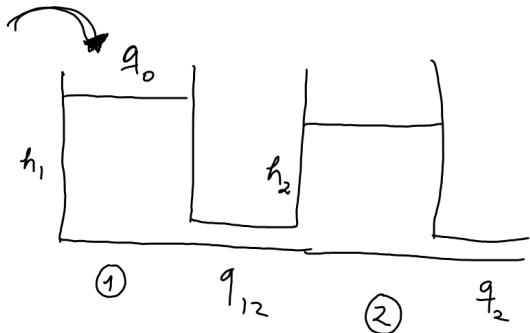


$$a = \frac{t_f}{4}$$

$$S(t) \Rightarrow 0.49 M(t) - 2 \cdot 0.49 M(t-a) +$$

$$+ 2 \times 0.49 M(t-3a) - 0.49 M(t-4a)$$





$$V_1 = A_1 h_1 \quad q_{12} = k_1 (h_1 - h_2)$$

$$V_2 = A_2 h_2 \quad q_2 = k_2 h_2$$

$$\frac{A_1}{A_2} = 1 \quad q_0 = 5 \text{ l/sec} \quad k_1 = \frac{4}{3} \quad k_2 = 12$$

$$A_2 = 8 \quad \frac{dV_1}{dt} = q_0 - q_{12} \quad \text{tanque 1.}$$

$$\frac{dA_1 h_1}{dt} = 5 - \frac{4}{3} (h_1 - h_2)$$

$$\rightarrow \frac{dh_1}{dt} = 5 - \frac{4}{3} (h_1 - h_2)$$

$$\frac{dV_2}{dt} = q_{12} - q_2$$

$$\frac{dA_2 h_2}{dt} = \frac{4}{3} (h_1 - h_2) - 12 h_2$$

$$\rightarrow \frac{dh_2}{dt} = \frac{4}{24} (h_1 - h_2) - \frac{12}{8} h_2$$

$$\frac{d}{dt} \begin{bmatrix} h_1 \\ h_2 \end{bmatrix} = \begin{bmatrix} -\frac{4}{3} & \frac{1}{3} \\ \frac{4}{24} & -\frac{40}{24} \end{bmatrix} \begin{bmatrix} h_1 \\ h_2 \end{bmatrix} + \begin{bmatrix} 5 \\ 0 \end{bmatrix}$$

$\begin{matrix} h_1(t) \\ h_2(t) \end{matrix}$ A $\begin{matrix} h_1(t) \\ h_2(t) \end{matrix}$ $b(t)$

 e^{At}

$$\bar{h}(t) = e^{At} h(0) + \int_0^t e^{A(t-z)} b(z) dz.$$

TEMA 4.-
EQUACIONES EN DERIVADAS PARCIALES

$z(x, y)$

$$\frac{\partial^2 z}{\partial x^2} - 3 \frac{\partial^2 z}{\partial x \partial y} + 6 \frac{\partial^2 z}{\partial y^2} = z(x, y).$$

$h(x, y, z)$

$$\frac{\partial h}{\partial z} - 6 \frac{\partial^2 h}{\partial x \partial y} + 12 \frac{\partial^3 h}{\partial x \partial y \partial z} = 0$$

Solución general puede no
Ser única.