

> restart

> $h := \frac{1}{2} \cdot (\sin(2t) \cdot \int (\cos(2 \cdot \text{tau})^2, \text{tau} = 0 .. t) - \cos(2 \cdot t) \cdot \int (\cos(2 \cdot \text{tau}) \cdot \sin(2 \cdot \text{tau}), \text{tau} = 0 .. t))$

$$h := \frac{\sin(2t) \left(\frac{\cos(2t) \sin(2t)}{4} + \frac{t}{2} \right) - \cos(2t) \left(\frac{1}{4} - \frac{\cos(2t)^2}{4} \right)}{2} \quad (1)$$

> $hh := \text{simplify}(h)$

$$hh := \frac{\sin(2t)t}{4} \quad (2)$$

> with(inttrans) :

> $H := \frac{s}{(s^2 + 4)^2}$

$$H := \frac{s}{(s^2 + 4)^2} \quad (3)$$

> $hhh := \text{invlaplace}(H, s, t)$

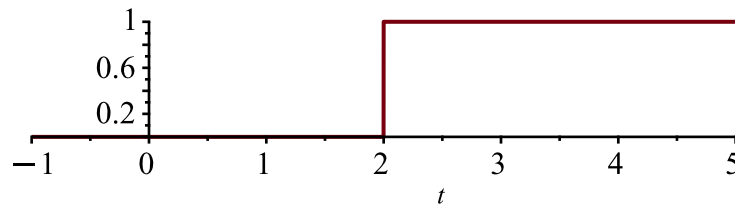
$$hhh := \frac{\sin(2t)t}{4} \quad (4)$$

> restart

> $u(t-2) := \text{Heaviside}(t-2)$

$$u(t-2) := \text{Heaviside}(t-2) \quad (5)$$

> $\text{plot}(u(t-2), t=-1..5, \text{scaling}=\text{CONSTRAINED})$



> with(inttrans) :

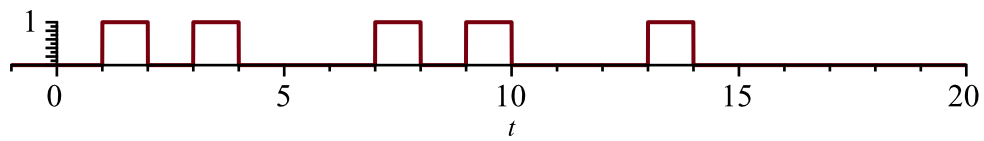
> $U := \text{laplace}(u(t-2), t, s)$

$$U := \frac{e^{-2s}}{s} \quad (6)$$

> $f := \text{Heaviside}(t-1) - \text{Heaviside}(t-2) + \text{Heaviside}(t-3) - \text{Heaviside}(t-4) + \text{Heaviside}(t-7) - \text{Heaviside}(t-8) + \text{Heaviside}(t-9) - \text{Heaviside}(t-10) + \text{Heaviside}(t-13) - \text{Heaviside}(t-14)$

$$f := \text{Heaviside}(t-1) - \text{Heaviside}(t-2) + \text{Heaviside}(t-3) - \text{Heaviside}(t-4) + \text{Heaviside}(t-7) - \text{Heaviside}(t-8) + \text{Heaviside}(t-9) - \text{Heaviside}(t-10) + \text{Heaviside}(t-13) - \text{Heaviside}(t-14) \quad (7)$$

> $\text{plot}(f, t=-1..20, \text{scaling}=\text{CONSTRAINED})$



$$\begin{aligned} &> F := \text{laplace}(f, t, s) \\ &F := \frac{e^{-s} - e^{-2s} + e^{-3s} - e^{-4s} + e^{-7s} - e^{-8s} + e^{-9s} - e^{-10s} + e^{-13s} - e^{-14s}}{s} \end{aligned} \quad (8)$$

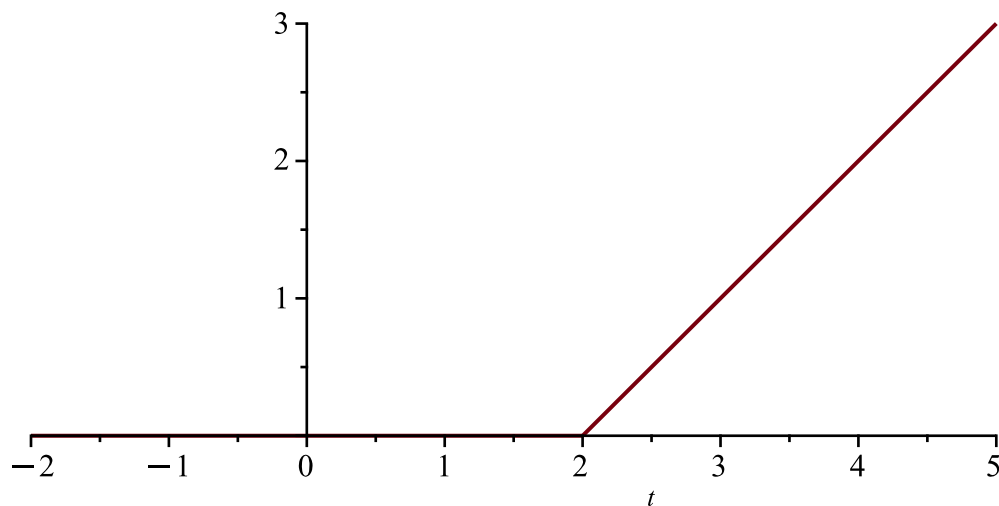
$$\begin{aligned} &> j := t - 2 \\ &j := t - 2 \end{aligned} \quad (9)$$

$$\begin{aligned} &> J := \text{laplace}(j, t, s) \\ &J := \frac{1}{s^2} - \frac{2}{s} \end{aligned} \quad (10)$$

$$\begin{aligned} &> r(t - 2) := (t - 2) \cdot \text{Heaviside}(t - 2) \\ &r(t - 2) := (t - 2) \text{Heaviside}(t - 2) \end{aligned} \quad (11)$$

$$\begin{aligned} &> R := \text{laplace}(r(t - 2), t, s) \\ &R := \frac{e^{-2s}}{s^2} \end{aligned} \quad (12)$$

$$> \text{plot}(r(t - 2), t = -2..5, \text{scaling} = \text{CONSTRAINED})$$



```
> k := Dirac(t - 2)
```

$$k := \text{Dirac}(t - 2)$$

(13)

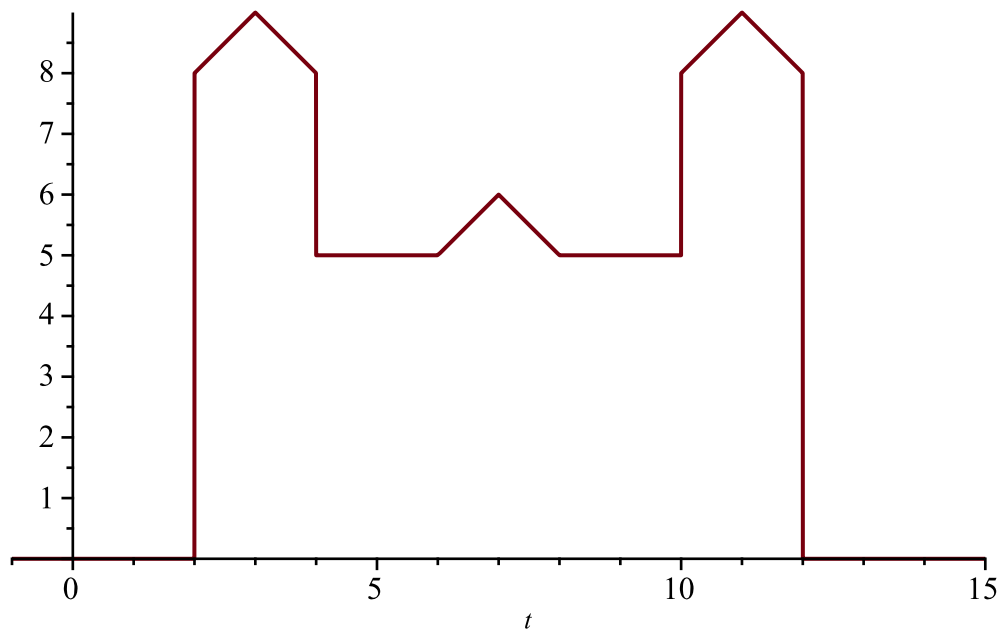
```
> K := laplace(k, t, s)
```

$$K := e^{-2s}$$

(14)

```
> restart
```

```
> Castillo := 8·Heaviside(t - 2) + (t - 2)·Heaviside(t - 2) - 2·(t - 3)·Heaviside(t - 3)
+ (t - 4)·Heaviside(t - 4) - 3·Heaviside(t - 4) + (t - 6)·Heaviside(t - 6) - 2·(t
- 7)·Heaviside(t - 7) + (t - 8)·Heaviside(t - 8) + 3·Heaviside(t - 10) + (t - 10)
·Heaviside(t - 10) - 2·(t - 11)·Heaviside(t - 11) + (t - 12)·Heaviside(t - 12) - 8
·Heaviside(t - 12) : plot(Castillo, t = -1 .. 15, scaling = CONSTRAINED)
```



```
> with(inttrans) :
```

```
> CASTILLO := laplace(Castillo, t, s)
```

$$\text{CASTILLO} := \frac{e^{-2s} + e^{-12s} - 2e^{-11s} + e^{-10s} + e^{-8s} - 2e^{-7s} + e^{-6s} + e^{-4s} - 2e^{-3s}}{s^2} \\ + \frac{8e^{-2s} - 8e^{-12s} + 3e^{-10s} - 3e^{-4s}}{s}$$

(15)

```
>
>
>
>
>
```