

```

> restart
> with(inttrans)
[addtable, fourier, fouriercos, fouriersin, hankel, hilbert, invfourier, invhilbert, invlaplace,
  invmellin, laplace, mellin, savetable, setup]

```

(1)

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> f := 5·t2

```

$$f := 5 t^2$$

(2)

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> F := laplace(f, t, s)

```

$$F := \frac{10}{s^3}$$

(3)

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> g := exp(4·t)

```

$$g := e^{4t}$$

(4)

```

> G := laplace(g, t, s)

```

$$G := \frac{1}{s - 4}$$

(5)

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> h := cos(2·t)

```

$$h := \cos(2 t)$$

(6)

```

> H := laplace(h, t, s)

```

$$H := \frac{s}{s^2 + 4}$$

(7)

```

> j := sin(2·t)

```

$$j := \sin(2 t)$$

(8)

```

> J := laplace(j, t, s)

```

$$J := \frac{2}{s^2 + 4}$$

(9)

```

> PP := 1 / (s2 + 2·s + 2)

```

$$PP := \frac{1}{s^2 + 2 s + 2}$$

(10)

```

> pp := invlaplace(PP, s, x)

```

$$pp := e^{-x} \sin(x)$$

(11)

```

> u := Heaviside(t - 4)

```

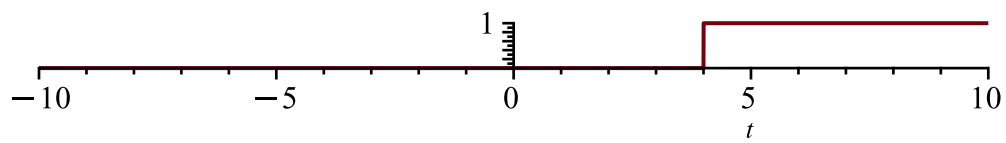
$$u := \text{Heaviside}(t - 4)$$

(12)

```

> plot(u, scaling = CONSTRAINED)

```



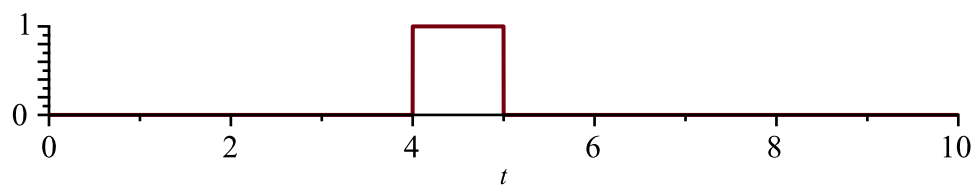
```
> U := laplace(u, t, s)
```

$$U := \frac{e^{-4s}}{s^2} \quad (13)$$

```
> v := invlaplace( (exp(-4*s)/s - exp(-5*s)/s), s, t)
```

$$v := \text{Heaviside}(t - 4) - \text{Heaviside}(t - 5) \quad (14)$$

```
> plot(v, t=0..10, scaling=CONSTRAINED)
```



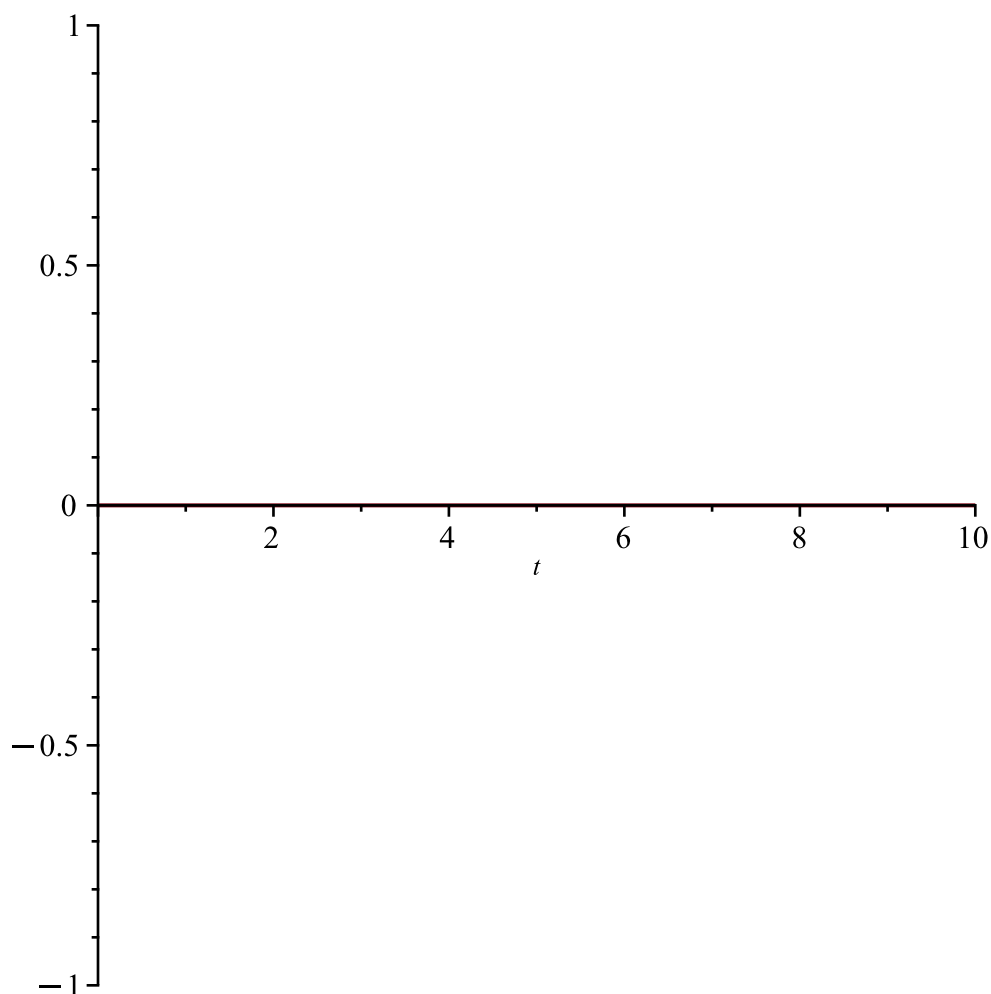
```
> d := Dirac(t - 6)
```

$d := \text{Dirac}(t - 6)$ **(15)**

```
> DD := laplace(d, t, s)
```

$DD := e^{-6s}$ **(16)**

```
> plot(d, t = 0 .. 10)
```



$$\begin{aligned} > F := \frac{(2 \cdot s^2 - 11 \cdot s + 13)}{(s - 1) \cdot (s - 2) \cdot (s - 4)} \\ & F := \frac{2 s^2 - 11 s + 13}{(s - 1) (s - 2) (s - 4)} \end{aligned} \quad (17)$$

$$\begin{aligned} > y := \text{invlaplace}(F, s, t) \\ & y := \frac{e^{2t}}{2} + \frac{4 e^t}{3} + \frac{e^{4t}}{6} \end{aligned} \quad (18)$$

$$\begin{aligned} > Ecua := \text{diff}(yy(t), t\$2) - 3 \cdot \text{diff}(yy(t), t) + 2 \cdot yy(t) = \exp(4 \cdot t) \\ & Ecua := \frac{d^2}{dt^2} yy(t) - 3 \frac{d}{dt} yy(t) + 2 yy(t) = e^{4t} \end{aligned} \quad (19)$$

$$\begin{aligned} > \text{Comprobar} := \text{simplify}(\text{eval}(\text{subs}(yy(t) = y, Ecua))) \\ & \text{Comprobar} := e^{4t} = e^{4t} \end{aligned} \quad (20)$$

$$\begin{aligned} > \text{TranLapEcua} := \text{subs}(D(yy)(0) = 3, yy(0) = 2, \text{laplace}(Ecua, t, s)) \\ & \text{TranLapEcua} := s^2 \mathcal{L}(yy(t), t, s) + 3 - 2s - 3s \mathcal{L}(yy(t), t, s) + 2 \mathcal{L}(yy(t), t, s) = \frac{1}{s - 4} \end{aligned} \quad (21)$$

$$\begin{aligned} > \text{Sollaplace} := \text{simplify}(\text{isolate}(\text{TranLapEcua}, \text{laplace}(yy(t), t, s))) \\ & \end{aligned} \quad (22)$$



$$Sollaplace := \mathcal{L}(yy(t), t, s) = \frac{2 s^2 - 11 s + 13}{s^3 - 7 s^2 + 14 s - 8}$$

(22)