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>
EXAMEN_6 2025-2-F2
> restart
1)
> Ecua := 2·x·y + y2 + (x2 + 2·x·y)·y'=0
    Ecua := 2 x y(x) + y(x)2 + (x2 + 2 x y(x))  $\left( \frac{dy}{dx} \right) = 0$  (1)

> with(DEtools):
> odeadvisor(Ecua)
[[ _homogeneous, class A ], _exact, _rational, [_Abel, 2nd type, class B]] (2)

Como exacta
> M := 2 x y + y2
    M := 2 x y + y2 (3)

> N := (x2 + 2 x y)
    N := x2 + 2 x y (4)

> Comprobar := diff(M, y) = diff(N, x)
    Comprobar := 2 x + 2 y = 2 x + 2 y (5)

> IntMx := expand(int(M, x))
    IntMx := y x2 + y2 x (6)

> SolGral := IntMx + int( (N - diff(IntMx, y)), y) = _C1
    SolGral := y x2 + y2 x = _C1 (7)

> SolFinal := y(x) · x2 + y(x)2 · x = _C1
    SolFinal := y(x) x2 + y(x)2 x = _C1 (8)

> DerSolFinal := isolate(diff(SolFinal, x), diff(y(x), x))
    DerSolFinal :=  $\frac{dy}{dx}$  y(x) =  $\frac{-2 x y(x) - y(x)^2}{x^2 + 2 x y(x)}$  (9)

> DerEcua := isolate(Ecua, diff(y(x), x))
    DerEcua :=  $\frac{dy}{dx}$  y(x) =  $\frac{-2 x y(x) - y(x)^2}{x^2 + 2 x y(x)}$  (10)

> ComprobarDos := rhs(DerSolFinal) - rhs(DerEcua) = 0
    ComprobarDos := 0 = 0 (11)

por coeficientes homogeneos
> Ecua
    2 x y(x) + y(x)2 + (x2 + 2 x y(x))  $\left( \frac{dy}{dx} \right) = 0$  (12)

> EcuaDos := simplify(isolate(eval(subs(y(x) = u(x) · x, Ecua)), diff(u(x), x)))
    EcuaDos :=  $\frac{du}{dx}$  u(x) =  $-\frac{3 u(x) (u(x) + 1)}{(1 + 2 u(x)) x}$  (13)

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$$> SolGralDos := \text{int}\left(\frac{1}{x}, x\right) + \text{int}\left(\frac{1}{\left(\frac{3 u \cdot (u + 1)}{(1 + 2 u)}\right)}, u\right) = -CI$$

$$SolGralDos := \ln(x) + \frac{\ln(u(u + 1))}{3} = -CI \quad (14)$$

$$> SolGralTres := \left(\text{subs}\left(u = \frac{y(x)}{x}, SolGralDos\right)\right)$$

$$SolGralTres := \ln(x) + \frac{\ln\left(\frac{y(x) \left(\frac{y(x)}{x} + 1\right)}{x}\right)}{3} = -CI \quad (15)$$

$$> SolGralCuatro := \text{expand}(\text{simplify}(\exp(\text{lhs}(SolGralTres)))^3 = -CI) \\ SolGralCuatro := y(x)x^2 + y(x)^2x = -CI \quad (16)$$

$$> SolFinal \\ y(x)x^2 + y(x)^2x = -CI \quad (17)$$

$$> restart \\ 2)$$

$$> Ecua := r \cdot \text{diff}(\theta(r), r) = \frac{(r^2 + a^2)}{r^2}$$

$$Ecua := r \left(\frac{d}{dr} \theta(r) \right) = \frac{a^2 + r^2}{r^2} \quad (18)$$

$$> \text{with(DEtools)} : \\ > \text{odeadvisor}(Ecua) \\ [_quadrature] \quad (19)$$

$$> IntFact := \text{intfactor}(Ecua) \\ IntFact := \frac{1}{r} \quad (20)$$

$$> M := -\text{rhs}(Ecua) \\ M := -\frac{a^2 + r^2}{r^2} \quad (21)$$

$$> N := r \\ N := r \quad (22)$$

$$> MM := IntFact \cdot M \\ MM := -\frac{a^2 + r^2}{r^3} \quad (23)$$

$$> NN := IntFact \cdot N \\ NN := 1 \quad (24)$$

$$> Comprobar := \text{diff}(MM, \theta) = \text{diff}(NN, r) \\ Comprobar := 0 = 0 \quad (25)$$

$$> IntNNtheta := \text{int}(NN, \theta)$$

$$IntNNtheta := \theta \quad (26)$$

> $SolGral := IntNNtheta + \text{int}((MM - \text{diff}(IntNNtheta, r)), r) = _C1$
 $SolGral := \theta + \frac{a^2}{2r^2} - \ln(r) = _C1$ (27)

> $SolFinal := \text{isolate}(SolGral, \theta)$
 $SolFinal := \theta = _C1 - \frac{a^2}{2r^2} + \ln(r)$ (28)

> $SolFinalDos := \theta(r) = \text{rhs}(SolFinal)$
 $SolFinalDos := \theta(r) = _C1 - \frac{a^2}{2r^2} + \ln(r)$ (29)

> $Ecua$
 $r \left(\frac{d}{dr} \theta(r) \right) = \frac{a^2 + r^2}{r^2}$ (30)

> $ComprobarDos := \text{simplify}(\text{eval}(\text{subs}(\theta(r) = \text{rhs}(SolFinalDos), \text{lhs}(Ecua) - \text{rhs}(Ecua)) = 0))$
 $ComprobarDos := 0 = 0$ (31)

> $restart$
3)
> $Ecua := y'' - 2 \cdot y' + y = x \cdot \sinh(x)$
 $Ecua := \frac{d^2}{dx^2} y(x) - 2 \frac{d}{dx} y(x) + y(x) = x \sinh(x)$ (32)

> $EcuaHom := \text{lhs}(Ecua) = 0$
 $EcuaHom := \frac{d^2}{dx^2} y(x) - 2 \frac{d}{dx} y(x) + y(x) = 0$ (33)

> $Q := \text{rhs}(Ecua)$
 $Q := x \sinh(x)$ (34)

> $EcuaCarac := m^2 - 2 \cdot m + 1 = 0$
 $EcuaCarac := m^2 - 2m + 1 = 0$ (35)

> $Raiz := \text{solve}(EcuaCarac)$
 $Raiz := 1, 1$ (36)

> $yy[1] := \exp(Raiz[1] \cdot x); yy[2] := x \cdot \exp(Raiz[1] \cdot x)$
 $yy_1 := e^x$
 $yy_2 := x e^x$ (37)

> with(linalg) :
> $WW := \text{wronskian}([yy[1], yy[2]], x)$
 $WW := \begin{bmatrix} e^x & x e^x \\ e^x & e^x + x e^x \end{bmatrix}$ (38)

> $BB := \text{array}([0, Q])$

$$BB := \begin{bmatrix} 0 & x \sinh(x) \end{bmatrix} \quad (39)$$

> $Para := \text{linsolve}(WW, BB)$

$$Para := \begin{bmatrix} -\frac{x^2 \sinh(x)}{e^x} & \frac{x \sinh(x)}{e^x} \end{bmatrix} \quad (40)$$

> $Aprima := Para[1]; Bprima := Para[2]$

$$Aprima := -\frac{x^2 \sinh(x)}{e^x}$$

$$Bprima := \frac{x \sinh(x)}{e^x} \quad (41)$$

> $SolGral := y(x) = \text{expand}(\text{simplify}((\text{int}(Aprima, x) + _C1) \cdot yy[1] + (\text{int}(Bprima, x) + _C2) \cdot yy[2]))$

$$SolGral := y(x) = -\frac{1}{8 e^x} - \frac{x}{8 e^x} + \frac{e^x x^3}{12} + x e^x _C2 + e^x _C1 \quad (42)$$

> $Comprobar := \text{simplify}(\text{eval}(\text{subs}(y(x) = \text{rhs}(SolGral), \text{lhs}(Ecua) - \text{rhs}(Ecua) = 0)))$

$$Comprobar := 0 = 0 \quad (43)$$

> *restart*

4)

> $H := \frac{(s^2 + 2 \cdot s + 5)}{(s^2 - 6 \cdot s + 10)}$

$$H := \frac{s^2 + 2 s + 5}{s^2 - 6 s + 10} \quad (44)$$

> *with(inttrans)* :

> $h := \text{expand}(\text{invlaplace}(H, s, t))$

$$h := \text{Dirac}(t) + 8 (e^t)^3 \cos(t) + 19 (e^t)^3 \sin(t) \quad (45)$$

> *restart*

5)

> $Ecua := \text{diff}(y(t), t\$2) + 4 \cdot y(t) = \cos(t - \text{Pi}) \cdot \text{Heaviside}(t - \text{Pi})$

$$Ecua := \frac{d^2}{dt^2} y(t) + 4 y(t) = -\cos(t) \text{Heaviside}(t - \pi) \quad (46)$$

> $CondIni := y(0) = 0, D(y)(0) = 1$

$$CondIni := y(0) = 0, D(y)(0) = 1 \quad (47)$$

> *with(inttrans)* :

> $EcuaTransLap := \text{subs}(CondIni, \text{laplace}(Ecua, t, s))$

$$EcuaTransLap := s^2 \mathcal{L}(y(t), t, s) - 1 + 4 \mathcal{L}(y(t), t, s) = \frac{e^{-s \pi} s}{s^2 + 1} \quad (48)$$

> $SolTransLap := \text{simplify}(\text{isolate}(EcuaTransLap, \text{laplace}(y(t), t, s)))$

$$(49)$$

$$SolTransLap := \mathcal{L}(y(t), t, s) = \frac{e^{-s\pi} s + s^2 + 1}{(s^2 + 1)(s^2 + 4)} \quad (49)$$

> $SolPart := \text{invlaplace}(SolTransLap, s, t)$

$$SolPart := y(t) = \frac{\sin(2t)}{2} - \frac{\text{Heaviside}(t - \pi)(\cos(t) + \cos(2t))}{3} \quad (50)$$

> $ComprobarUno := \text{simplify}(\text{subs}(t=0, SolPart))$

$$ComprobarUno := y(0) = 0 \quad (51)$$

> $ComprobarDos := D(y)(0) = \text{simplify}(\text{subs}(t=0, \text{rhs}(\text{diff}(SolPart, t))))$

$$ComprobarDos := D(y)(0) = 1 \quad (52)$$

> $CondIni$

$$y(0) = 0, D(y)(0) = 1 \quad (53)$$

> $ComprobarTres := \text{simplify}(\text{eval}(\text{subs}(y(t) = \text{rhs}(SolPart), \text{lhs}(Ecua) - \text{rhs}(Ecua) = 0)))$

$$ComprobarTres := 0 = 0 \quad (54)$$

> $restart$

6)

> $Ecua := \text{diff}(y(t), t\$3) - 2 \cdot \text{diff}(y(t), t\$2) + y(t) = \cos(t)$

$$Ecua := \frac{d^3}{dt^3} y(t) - 2 \frac{d^2}{dt^2} y(t) + y(t) = \cos(t) \quad (55)$$

> $CondIni := y(0) = 1, D(y)(0) = 0, D(D(y))(0) = 2$

$$CondIni := y(0) = 1, D(y)(0) = 0, D^{(2)}(y)(0) = 2 \quad (56)$$

a) convertir a un sistema

> $FuncUno := y(t) = yy[1](t)$

$$FuncUno := y(t) = yy_1(t) \quad (57)$$

> $\text{diff}(y(t), t) := \text{diff}(yy[1](t), t) = yy[2](t)$

$$\frac{d}{dt} y(t) := \frac{d}{dt} yy_1(t) = yy_2(t) \quad (58)$$

> $\text{diff}(y(t), t\$2) := \text{diff}(yy[2](t), t) = yy[3](t)$

$$\frac{d^2}{dt^2} y(t) := \frac{d}{dt} yy_2(t) = yy_3(t) \quad (59)$$

> $\text{diff}(y(t), t\$3) := \text{diff}(yy[3](t), t) = -yy[1](t) + 2 \cdot yy[3](t) + \cos(t)$

$$\frac{d^3}{dt^3} y(t) := \frac{d}{dt} yy_3(t) = -yy_1(t) + 2yy_3(t) + \cos(t) \quad (60)$$

> $Ecua$

$$\frac{d^3}{dt^3} y(t) - 2 \frac{d^2}{dt^2} y(t) + y(t) = \cos(t) \quad (61)$$

> $Sistema := ([\text{diff}(yy[1](t), t) = yy[2](t), \text{diff}(yy[2](t), t) = yy[3](t), \text{diff}(yy[3](t), t) = -yy[1](t) + 2 \cdot yy[3](t) + \cos(t)]) : Sistema[1]; Sistema[2]; Sistema[3]$

$$\frac{d}{dt} yy_1(t) = yy_2(t)$$

$$\begin{aligned} \frac{d}{dt} yy_2(t) &= yy_3(t) \\ \frac{d}{dt} yy_3(t) &= -yy_1(t) + 2yy_3(t) + \cos(t) \end{aligned} \quad (62)$$

> $CondIniDos := yy[1](0) = 1, yy[2](0) = 0, yy[3](0) = 2$
 $CondIniDos := yy_1(0) = 1, yy_2(0) = 0, yy_3(0) = 2$ (63)

b) resolver con Transformada de Laplace

> $with(inttrans):$
> $SistTransdLap[1] := subs(CondIniDos, laplace(Sistema[1], t, s))$
 $SistTransdLap_1 := s \mathcal{L}(yy_1(t), t, s) - 1 = \mathcal{L}(yy_2(t), t, s)$ (64)

> $SistTransdLap[2] := subs(CondIniDos, laplace(Sistema[2], t, s))$
 $SistTransdLap_2 := s \mathcal{L}(yy_2(t), t, s) = \mathcal{L}(yy_3(t), t, s)$ (65)

> $SistTransdLap[3] := subs(CondIniDos, laplace(Sistema[3], t, s))$
 $SistTransdLap_3 := s \mathcal{L}(yy_3(t), t, s) - 2 = -\mathcal{L}(yy_1(t), t, s) + 2 \mathcal{L}(yy_3(t), t, s) + \frac{s}{s^2 + 1}$ (66)

> $SistemaDos := SistTransdLap[1], SistTransdLap[2], SistTransdLap[3];$
 $SistemaDos := s \mathcal{L}(yy_1(t), t, s) - 1 = \mathcal{L}(yy_2(t), t, s), s \mathcal{L}(yy_2(t), t, s) = \mathcal{L}(yy_3(t), t, s),$ (67)

$$s \mathcal{L}(yy_3(t), t, s) - 2 = -\mathcal{L}(yy_1(t), t, s) + 2 \mathcal{L}(yy_3(t), t, s) + \frac{s}{s^2 + 1}$$

> $with(linalg):$
> $SolTransLap := solve([SistemaDos], [laplace(yy[1](t), t, s), laplace(yy[2](t), t, s),$
 $laplace(yy[3](t), t, s)])$
 $SolTransLap := \left[\left[\begin{array}{l} \mathcal{L}(yy_1(t), t, s) = \frac{s^4 - 2s^3 + 3s^2 - s + 2}{s^5 - 2s^4 + s^3 - s^2 + 1}, \mathcal{L}(yy_2(t), t, s) \\ = \frac{2s^3 + 2s - 1}{s^5 - 2s^4 + s^3 - s^2 + 1}, \mathcal{L}(yy_3(t), t, s) = \frac{s(2s^3 + 2s - 1)}{s^5 - 2s^4 + s^3 - s^2 + 1} \end{array} \right] \right]$ (68)

> $SolPart[1] := simplify(invlaplace(SolTransLap[1, 1], s, t))$
 $SolPart_1 := yy_1(t) = \frac{e^{\frac{t}{2}} \sinh\left(\frac{t\sqrt{5}}{2}\right)\sqrt{5}}{5} + \frac{11e^{\frac{t}{2}} \cosh\left(\frac{t\sqrt{5}}{2}\right)}{5} - \frac{3e^t}{2} + \frac{3\cos(t)}{10} - \frac{\sin(t)}{10}$ (69)

> $SolPart[2] := simplify(invlaplace(SolTransLap[1, 2], s, t))$
 $SolPart_2 := yy_2(t) = \frac{6e^{\frac{t}{2}} \sinh\left(\frac{t\sqrt{5}}{2}\right)\sqrt{5}}{5} + \frac{8e^{\frac{t}{2}} \cosh\left(\frac{t\sqrt{5}}{2}\right)}{5} - \frac{3e^t}{2} - \frac{\cos(t)}{10} - \frac{3\sin(t)}{10}$ (70)

> $SolPart[3] := simplify(invlaplace(SolTransLap[1, 3], s, t))$

$$SolPart_3 := yy_3(t) = \frac{7 e^{\frac{t}{2}} \sinh\left(\frac{t \sqrt{5}}{2}\right) \sqrt{5}}{5} + \frac{19 e^{\frac{t}{2}} \cosh\left(\frac{t \sqrt{5}}{2}\right)}{5} - \frac{3 e^t}{2} - \frac{3 \cos(t)}{10} + \frac{\sin(t)}{10} \quad (71)$$

> $SolFinal := y(t) = rhs(SolPart[1])$

$$SolFinal := y(t) = \frac{e^{\frac{t}{2}} \sinh\left(\frac{t \sqrt{5}}{2}\right) \sqrt{5}}{5} + \frac{11 e^{\frac{t}{2}} \cosh\left(\frac{t \sqrt{5}}{2}\right)}{5} - \frac{3 e^t}{2} + \frac{3 \cos(t)}{10} - \frac{\sin(t)}{10} \quad (72)$$

> *restart*

7)

> $Ecua := diff(u(x, t), x\$2) = diff(u(x, t), t) + 2 \cdot u(x, t)$

$$Ecua := \frac{\partial^2}{\partial x^2} u(x, t) = \frac{\partial}{\partial t} u(x, t) + 2 u(x, t) \quad (73)$$

> $EcuaDos := eval(subs(u(x, t) = F(x) \cdot G(t), Ecua))$

$$EcuaDos := \left(\frac{d^2}{dx^2} F(x) \right) G(t) = F(x) \left(\frac{d}{dt} G(t) \right) + 2 F(x) G(t) \quad (74)$$

> $EcuaSep := \frac{lhs(EcuaDos)}{F(x) \cdot G(t)} = simplify\left(\frac{rhs(EcuaDos)}{F(x) \cdot G(t)} \right)$

$$EcuaSep := \frac{\frac{d^2}{dx^2} F(x)}{F(x)} = \frac{\frac{d}{dt} G(t) + 2 G(t)}{G(t)} \quad (75)$$

a) para cte sep igual a 4

> $EcuaPosX := lhs(EcuaSep) = 4$

$$EcuaPosX := \frac{\frac{d^2}{dx^2} F(x)}{F(x)} = 4 \quad (76)$$

> $EcuaPosT := rhs(EcuaSep) = 4$

$$EcuaPosT := \frac{\frac{d}{dt} G(t) + 2 G(t)}{G(t)} = 4 \quad (77)$$

> $SolPosX := dsolve(EcuaPosX)$

$$SolPosX := F(x) = c_1 e^{-2x} + c_2 e^{2x} \quad (78)$$

> $SolPosT := dsolve(EcuaPosT)$

$$SolPosT := G(t) = c_1 e^{2t} \quad (79)$$

> $SolPosGral := u(x, t) = rhs(SolPosX) \cdot subs(c_1 = 1, rhs(SolPosT))$

$$(80)$$

$$SolPosGral := u(x, t) = (c_1 e^{-2x} + c_2 e^{2x}) e^{2t} \quad (80)$$

para cte sep igual a -4

> $EcuaNegX := lhs(EcuaSep) = -4$

$$EcuaNegX := \frac{\frac{d^2}{dx^2} F(x)}{F(x)} = -4 \quad (81)$$

> $EcuaNegT := rhs(EcuaSep) = -4$

$$EcuaNegT := \frac{\frac{d}{dt} G(t) + 2 G(t)}{G(t)} = -4 \quad (82)$$

> $SolNegX := dsolve(EcuaNegX)$

$$SolNegX := F(x) = c_1 \sin(2x) + c_2 \cos(2x) \quad (83)$$

> $SolNegT := dsolve(EcuaNegT)$

$$SolNegT := G(t) = c_1 e^{-6t} \quad (84)$$

> $SolNegGral := u(x, t) = rhs(SolNegX) \cdot subs(c_1 = 1, rhs(SolNegT))$

$$SolNegGral := u(x, t) = (c_1 \sin(2x) + c_2 \cos(2x)) e^{-6t} \quad (85)$$

> *restart*

8)

> $f := x^2 + x$

$$f := x^2 + x \quad (86)$$

> $L := \frac{\text{Pi}}{2}$

$$L := \frac{\pi}{2} \quad (87)$$

> $a[0] := \frac{1}{L} \cdot int(f, x = -L .. L)$

$$a_0 := \frac{\pi^2}{6} \quad (88)$$

> $a[n] := subs(\sin(n \cdot \text{Pi}) = 0, \cos(n \cdot \text{Pi}) = (-1)^n, \frac{1}{L} \cdot int(f \cdot \cos\left(\frac{n \cdot \text{Pi}}{L} \cdot x\right), x = -L .. L))$

$$a_n := \frac{(-1)^n}{n^2} \quad (89)$$

> $b[n] := subs(\sin(n \cdot \text{Pi}) = 0, \cos(n \cdot \text{Pi}) = (-1)^n, \frac{1}{L} \cdot int(f \cdot \sin\left(\frac{n \cdot \text{Pi}}{L} \cdot x\right), x = -L .. L))$

$$b_n := -\frac{(-1)^n}{n} \quad (90)$$

> $STF5 := \frac{a[0]}{2} + sum(a[n] \cdot \cos\left(\frac{n \cdot \text{Pi}}{L} \cdot x\right) + b[n] \cdot \sin\left(\frac{n \cdot \text{Pi}}{L} \cdot x\right), n = 1 .. 5)$

$$STF5 := \frac{\pi^2}{12} - \cos(2x) + \sin(2x) + \frac{\cos(4x)}{4} - \frac{\sin(4x)}{2} - \frac{\cos(6x)}{9} + \frac{\sin(6x)}{3} + \frac{\cos(8x)}{16} - \frac{\sin(8x)}{4} - \frac{\cos(10x)}{25} + \frac{\sin(10x)}{5} \quad (91)$$

> restart

FIN EXAMEN